

Camera Sensors

Peter D. Kozma – ELTE IK

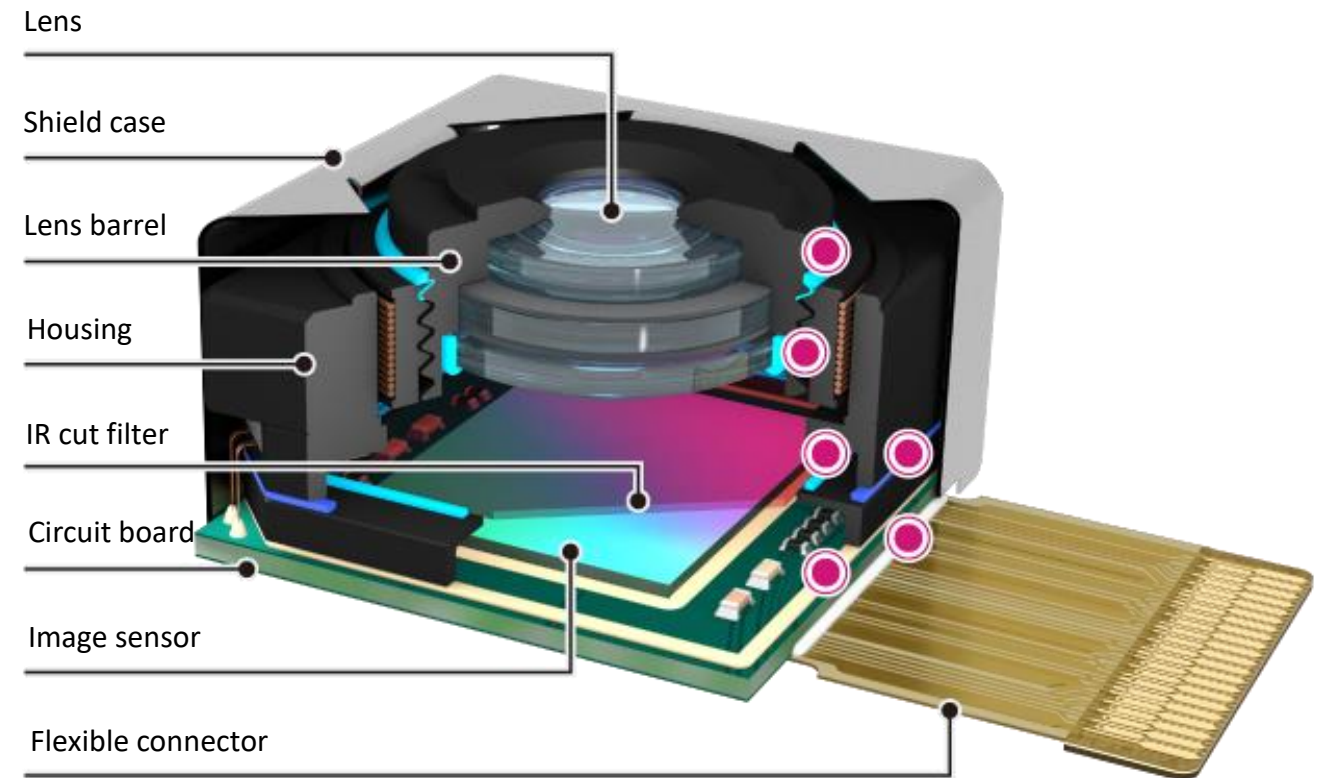
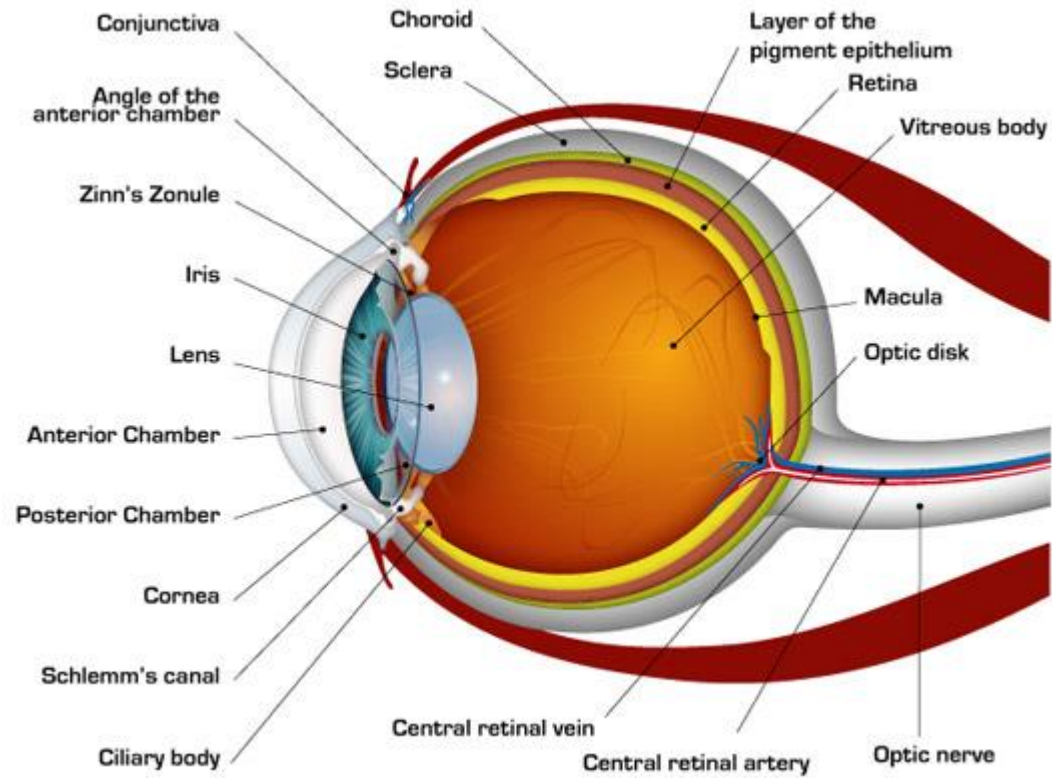
Content overview



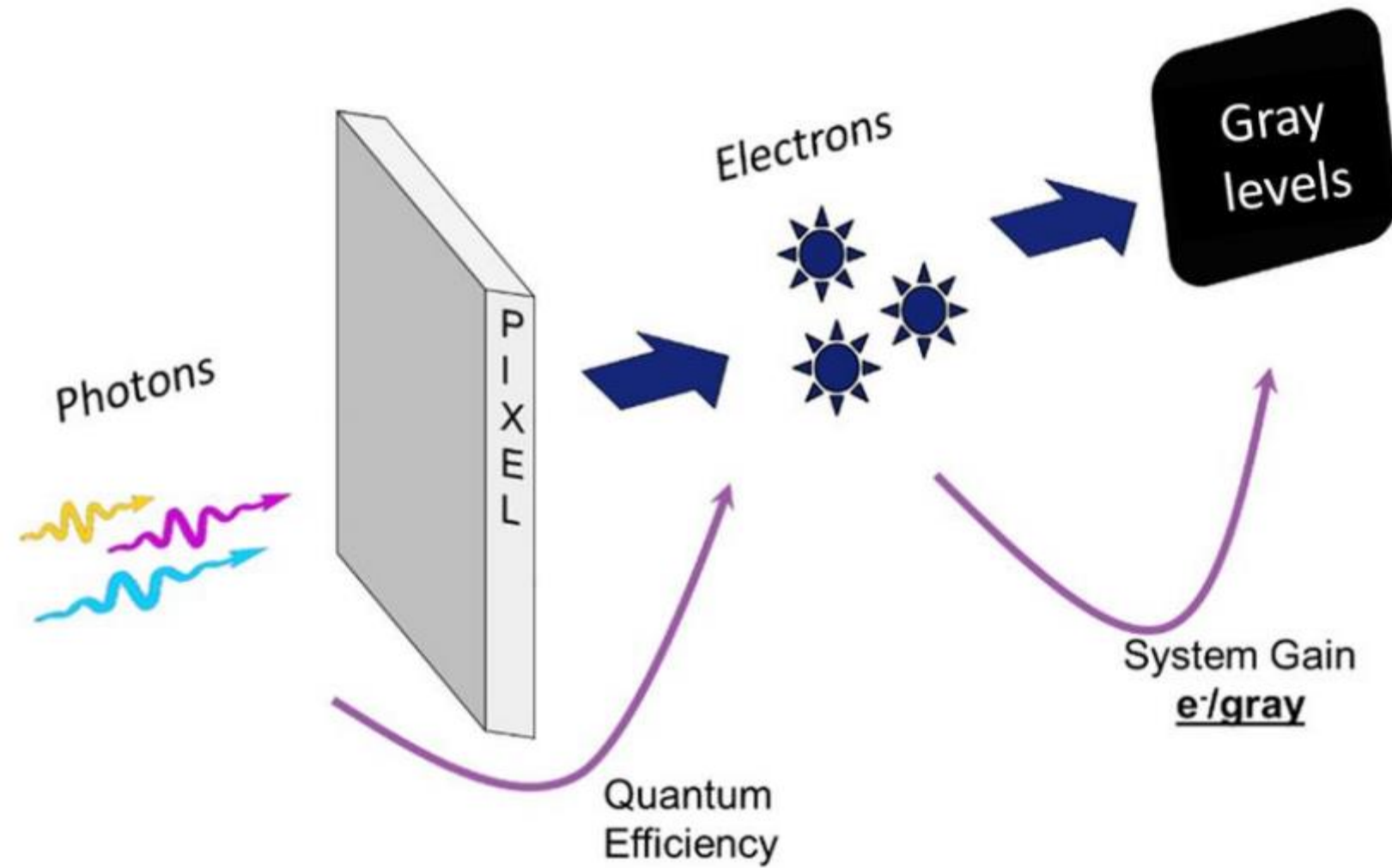
An aerial, top-down view of a city street intersection. The image is dark and semi-transparent, serving as a background for the text. It shows a multi-lane road with white lane markings and crosswalks. Several vehicles are visible: a white van in the upper center, a white sedan in the lower center, and a white SUV on the right side. Pedestrians are seen crossing the street at various points. Streetlights and traffic signals are also visible. The overall scene is a busy urban environment.

How does a camera work?

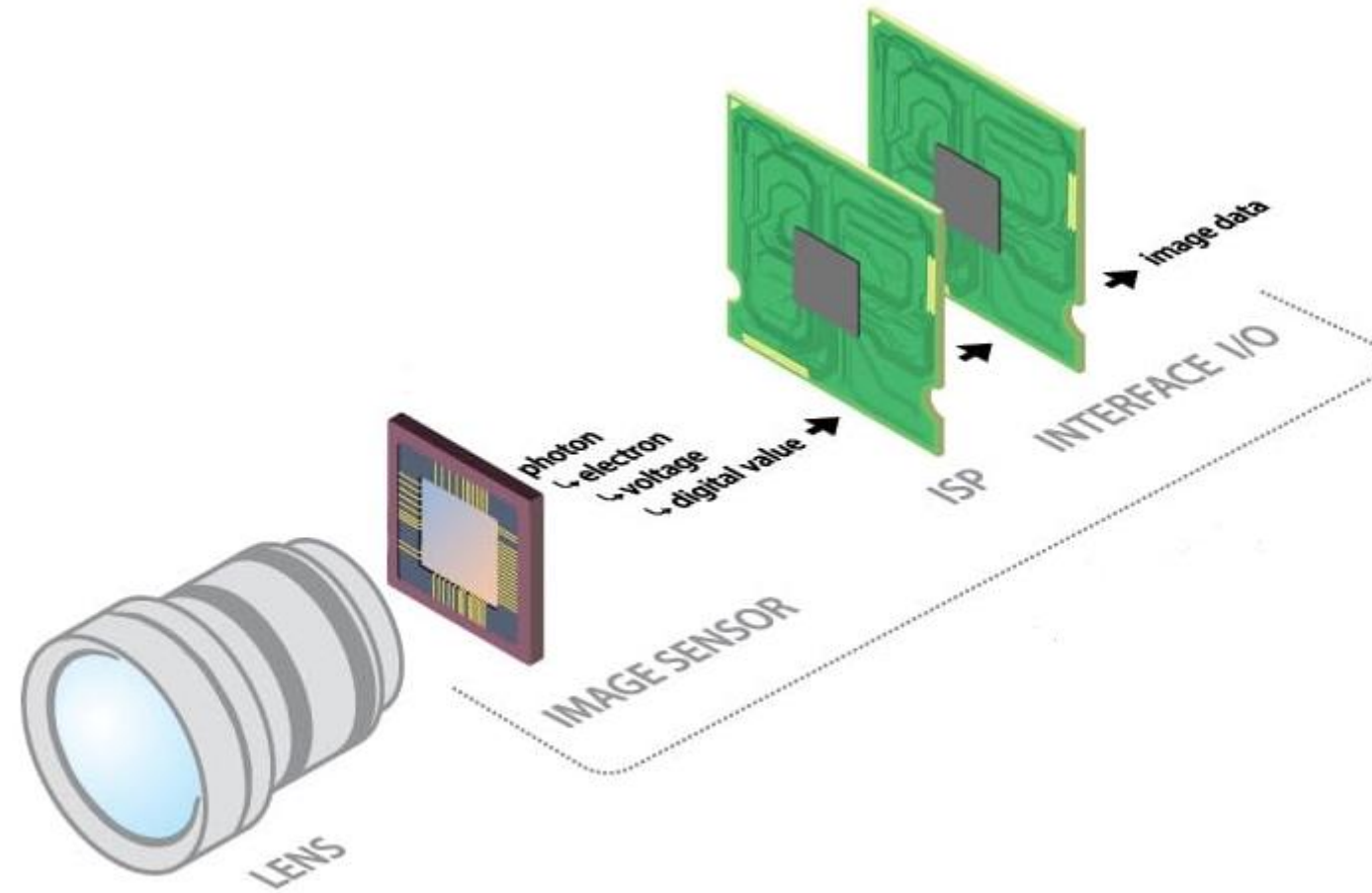
Human eye and camera sensor



We all know that



Camera components

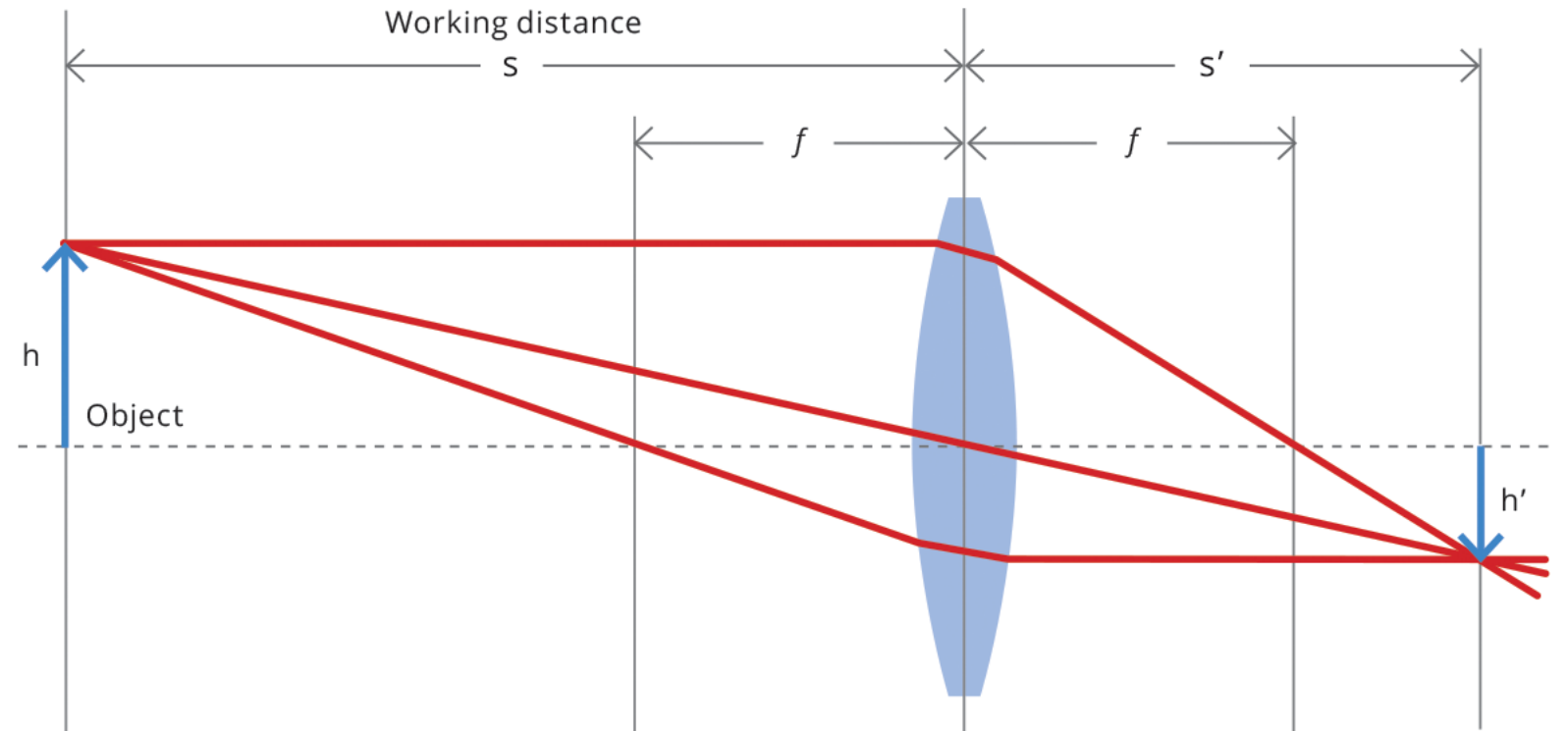


An aerial, top-down view of a city street intersection. The scene is dimly lit, appearing as a dark, monochromatic image. In the center, a white van is driving towards the viewer. To its right, a white sedan is driving away. Further right, another white sedan is visible. In the bottom right corner, a red fire hydrant is prominent. Pedestrians are seen crossing the street at various points. The road has white lane markings and crosswalks. The overall composition is centered around the word "Optics" which is overlaid in the middle of the image.

Optics

Thin lens- and paraxial approximation

- **Focal length (f):** the distance from the center of the lens to the principal foci (or focal points) of the lens
- **Working distance (s):** object to lens distance where the image is at its sharpest focus
- **Focal distance (s')**: lens to sensor distance where the image is at its sharpest focus
- **Depth of Field (DoF):** maximum range where the object appears to be in acceptable focus
- **Magnification (M):** ratio between object (h) and its image (h')
- **Resolution:** minimum distance between two points that can still be distinguished as separate points
- **Field of View (FoV):** total area that can be viewed by the lens and imaged onto the camera sensor
- **F-number (F/#):** the ratio of the focal length (f) to the diameter (d) of the aperture



$$\frac{1}{s'} - \frac{1}{s} = \frac{1}{f}$$

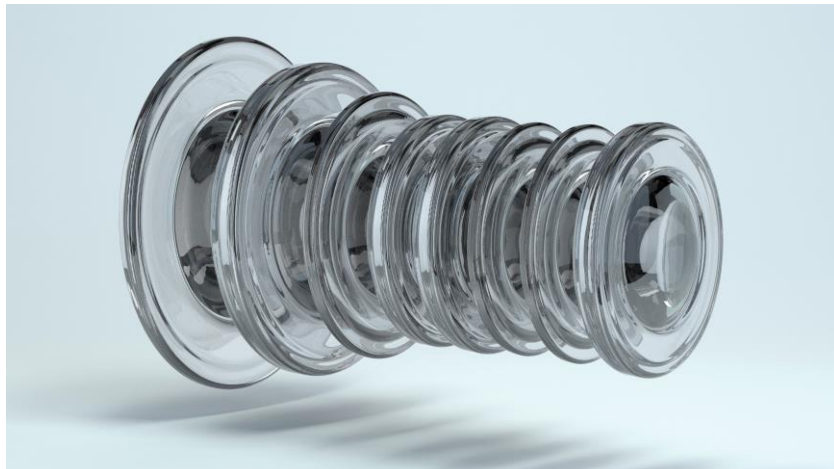
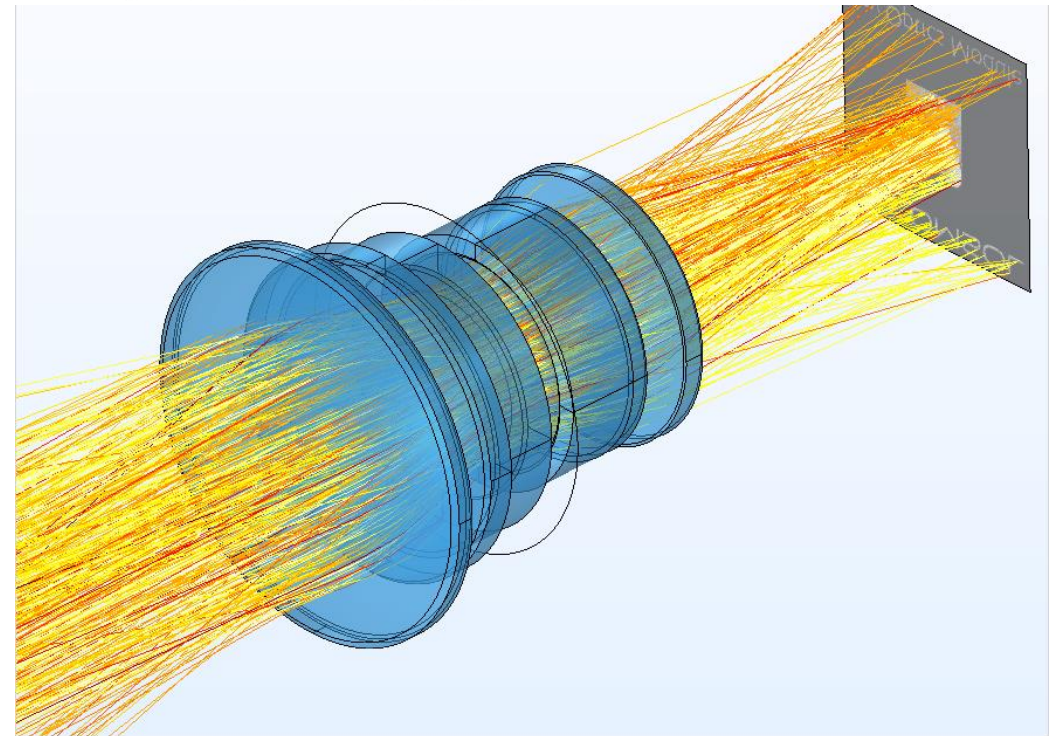
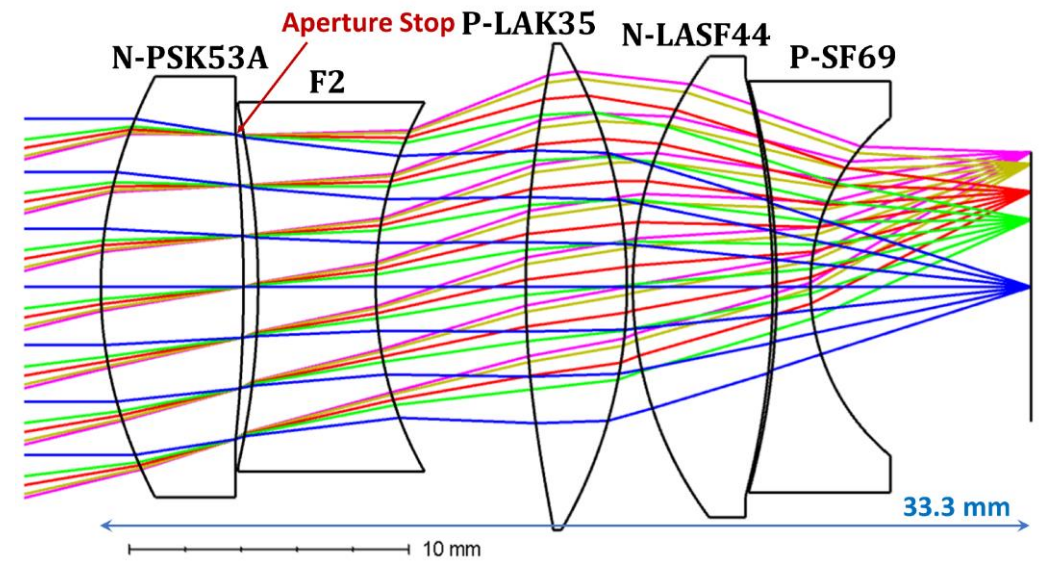
$$s = \frac{f(M - 1)}{M}$$

$$F/\# = \frac{f}{d}$$

Real world optics

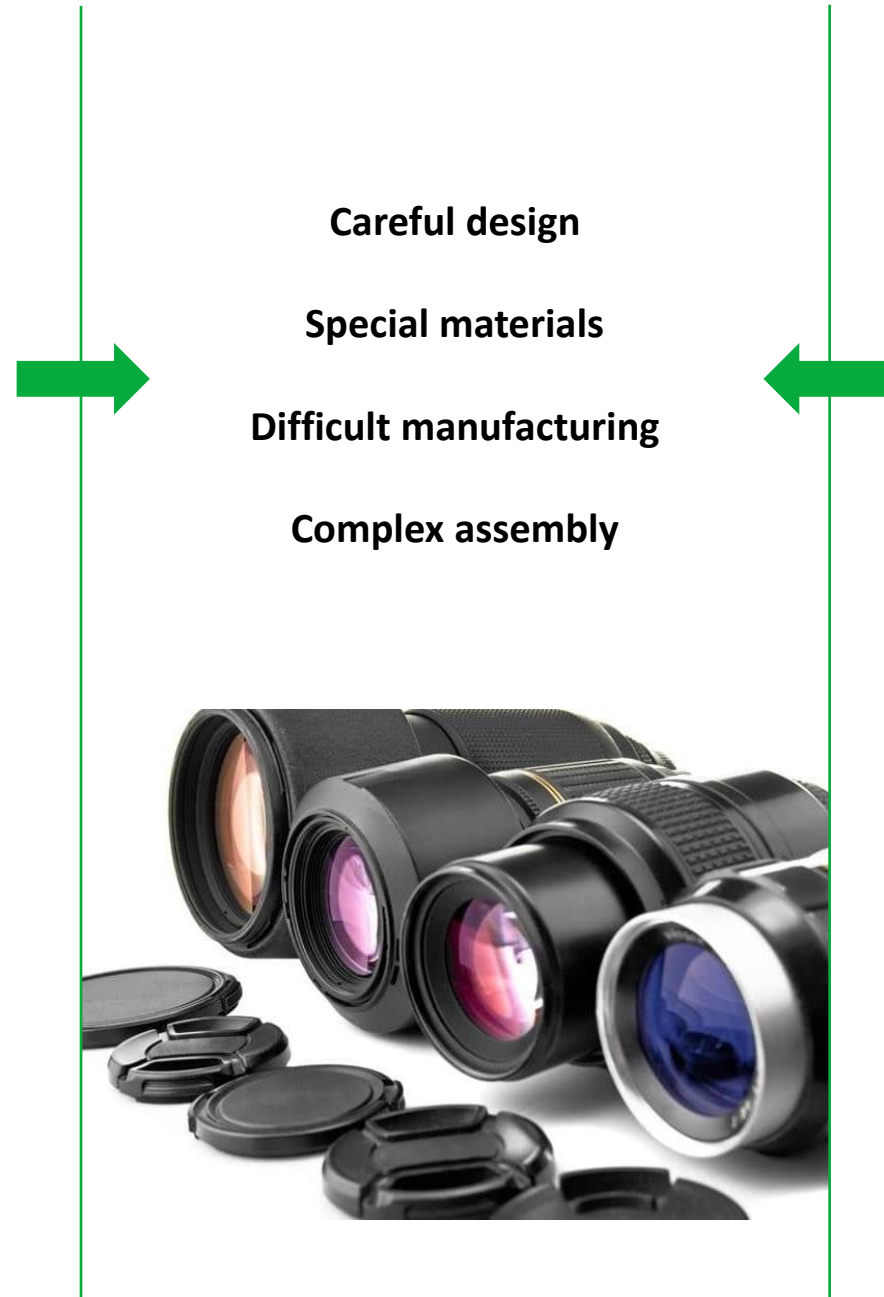
- **Ray tracing: design analysis and optimization**

- Zemax OpticStudio: zemax.com
- Code V: synopsys.com/optical-solutions/codev.html
- OSLO: lambdares.com/oslo
- TracePro: lambdares.com/tracepro
- Comsol Multiphysics: comsol.com/ray-optics-module



Why is it so complex?

- **Difficult requirements**
 - High resolution
 - Special working distance
 - Special wavelength
 - Variable focal distance
 - High FoV
 - Large DoF
 - Miniaturization
 - Cost optimization



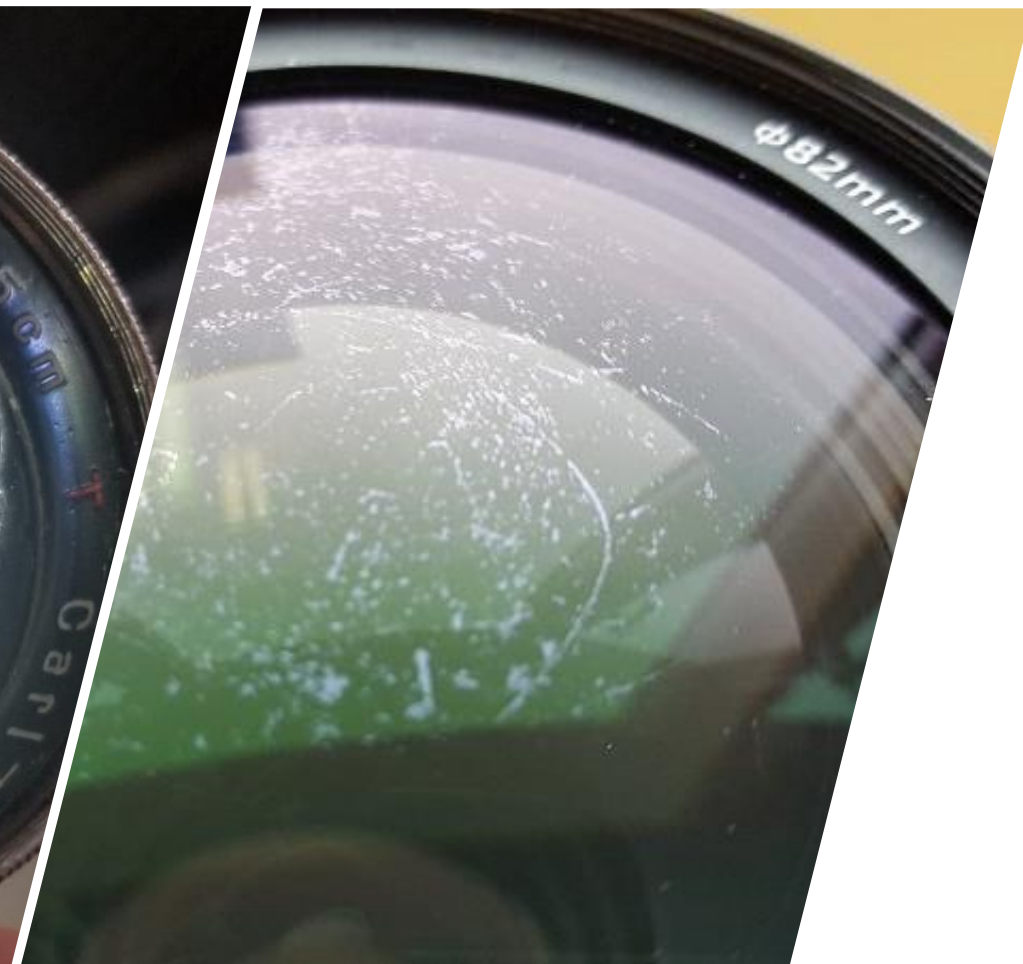
- **Potential aberrations**
 - Physical aberrations
 - Spherical aberrations
 - Chromatic aberrations
 - Astigmatism
 - Coma
 - Field curvature
 - Distortion
 - Low contrast and resolution
 - Vignetting

Physical aberrations

- Effects
 - Stray light (flare)
 - Loss of sharpness (blurring)
 - Reduced contrast (haze)
 - Washed-out colors
- Correction possibilities
 - Cleaning
 - Repair
 - Replacement
 - Preventive measures
 - Software correction

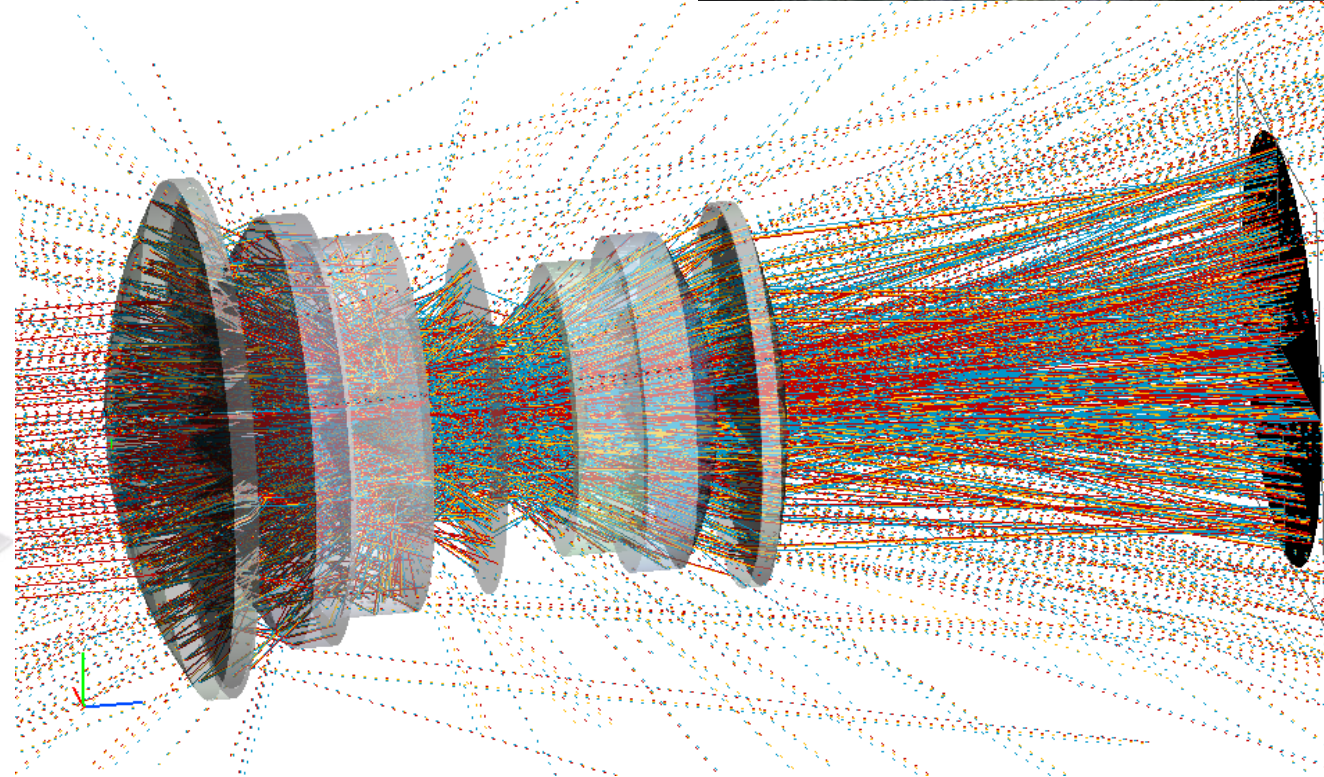


Dirt, dust, scratches, inhomogeneities



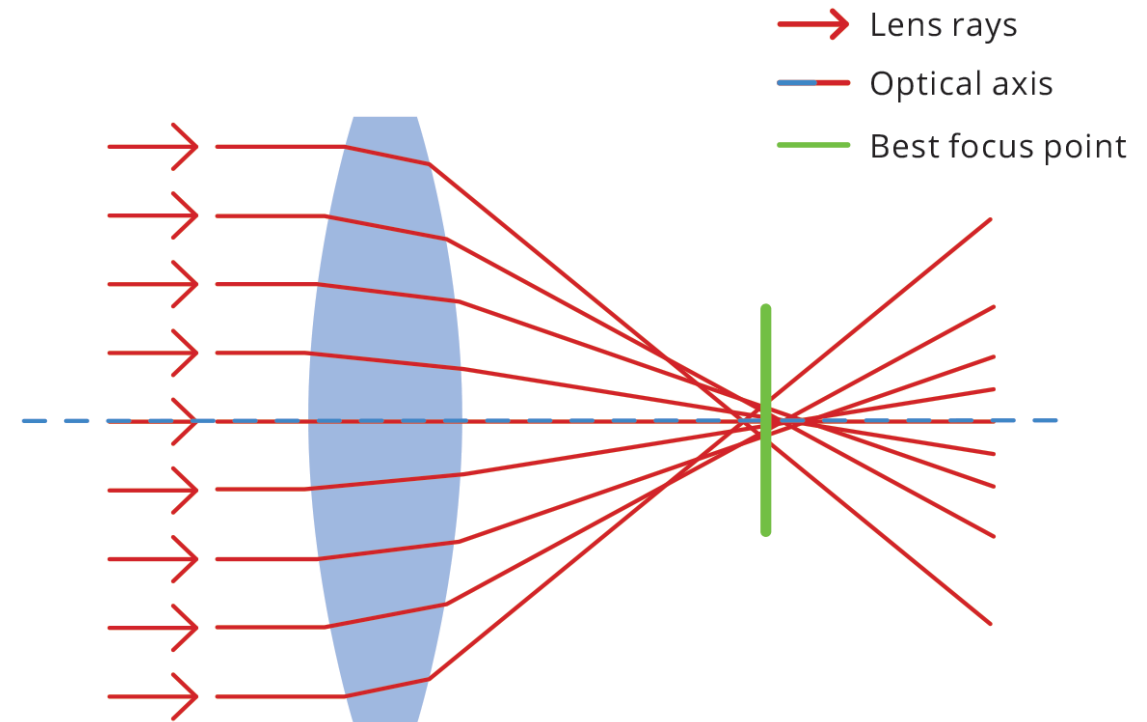
Damaged optical coating

Physical aberrations



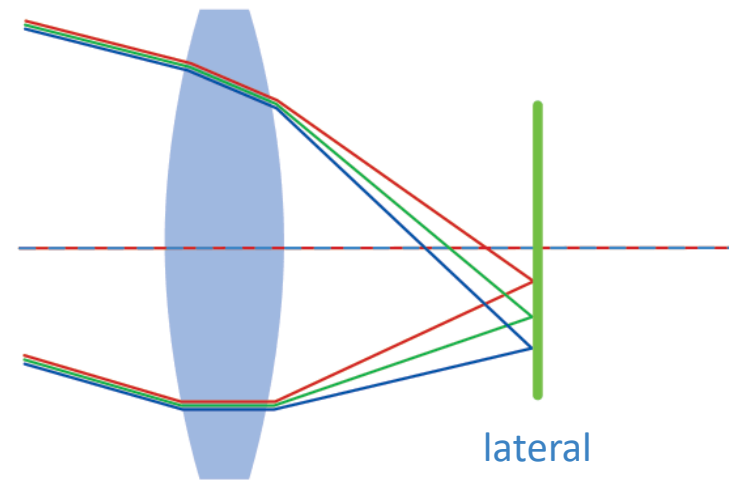
Spherical aberrations

- Effects
 - Loss of sharpness (blurring)
 - Reduced contrast (haze)
 - Halo around bright objects
- Correction possibilities
 - Aperture reduction
 - Replacement to aspheric lens
 - Correction lens
 - Software correction

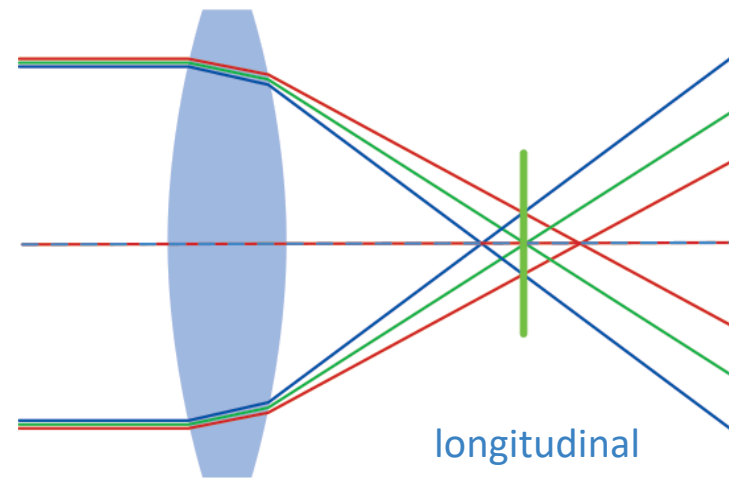
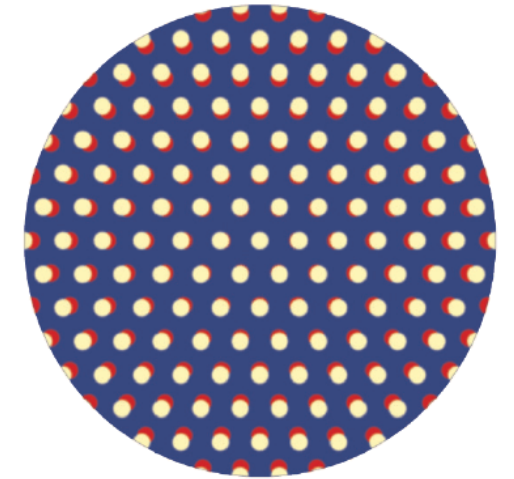


Chromatic aberration

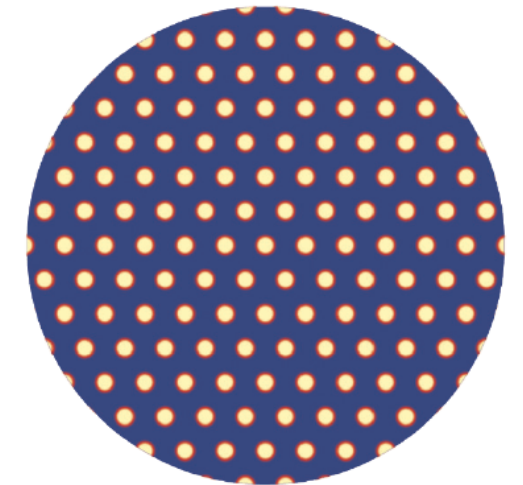
- Effects
 - Color fringing
 - Loss of sharpness (blurring)
 - Reduced contrast (haze)
- Correction possibilities
 - Aperture reduction
 - Replacement to achromatic lens
 - Correction lens
 - Software correction



█ RGB color rays
█ Optical axis
█ Best focus point

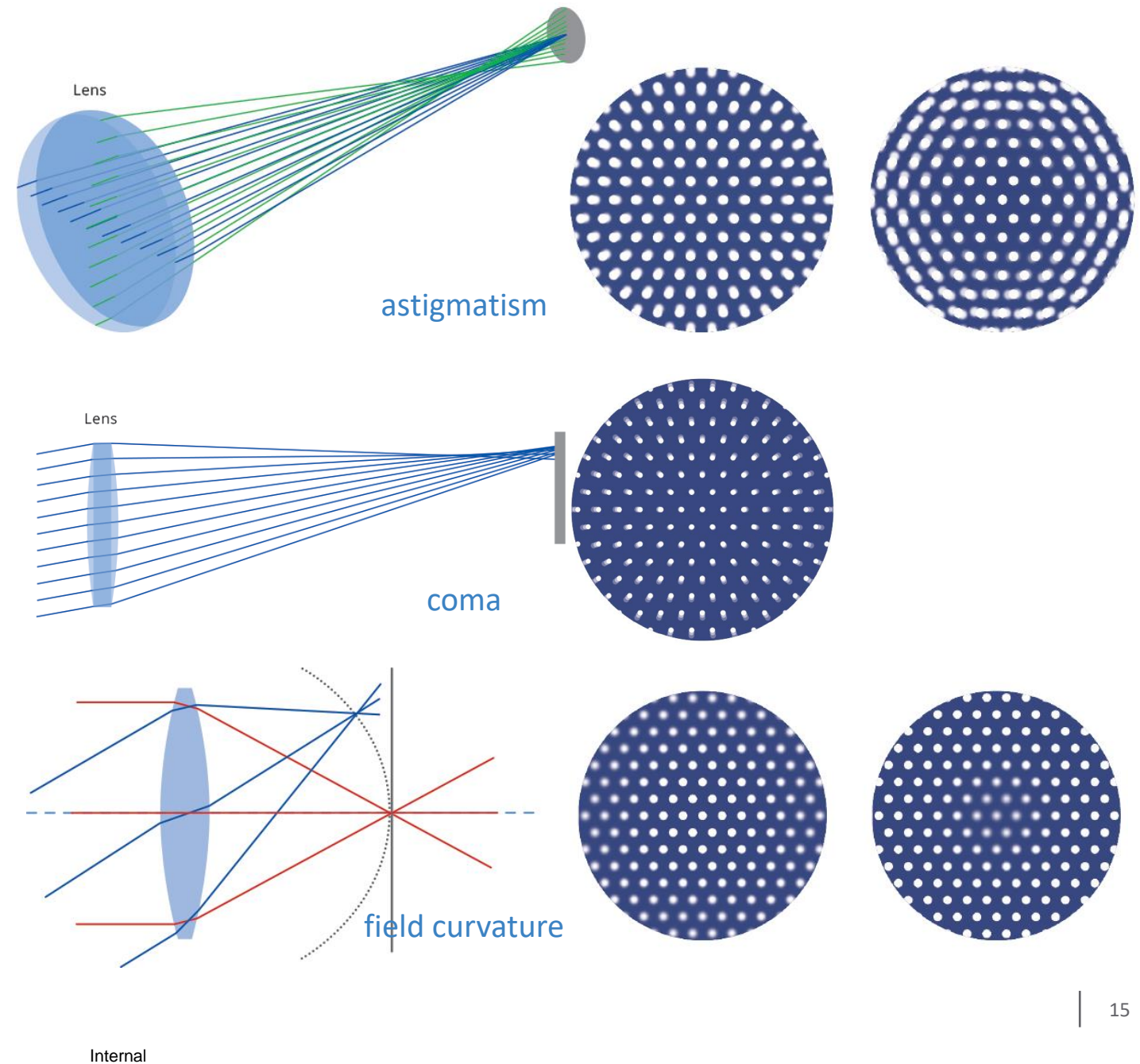


█ RGB color rays
█ Optical axis
█ Best focus point



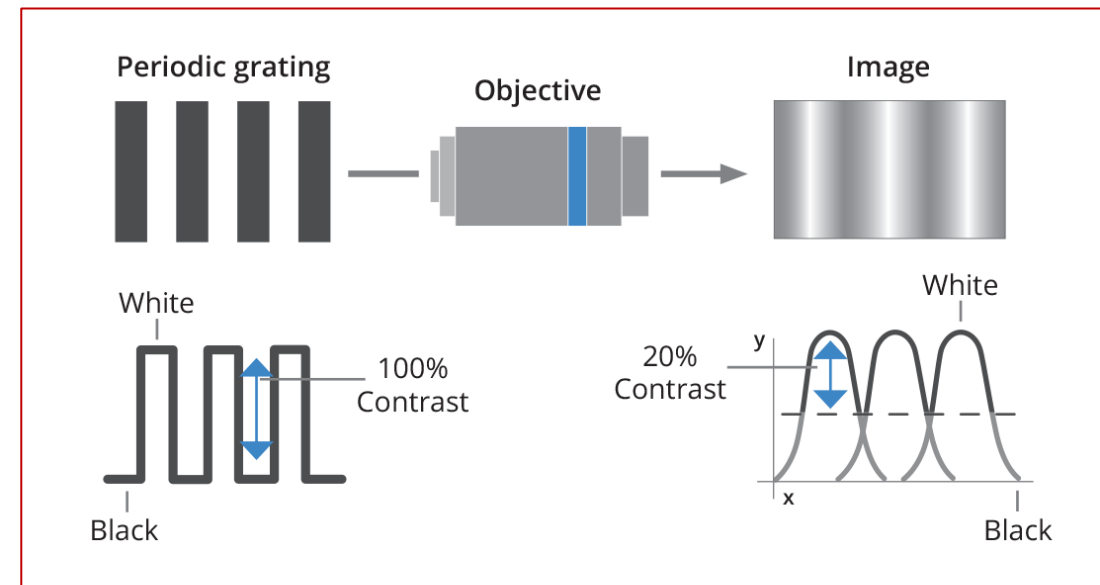
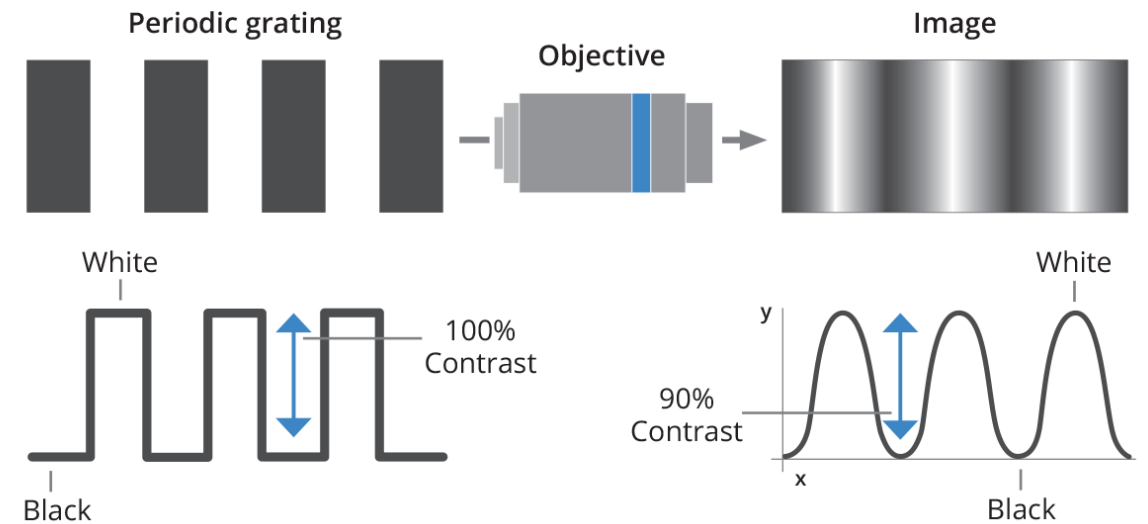
Astigmatism, coma, field curvature

- Effects
 - Loss of sharpness (blurring)
 - Reduced contrast (haze)
- Correction possibilities
 - Aperture reduction
 - Replacement of lens
 - Correction lens
 - Software correction



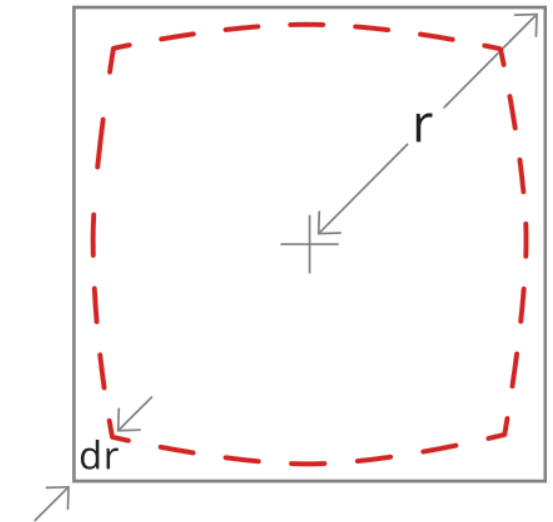
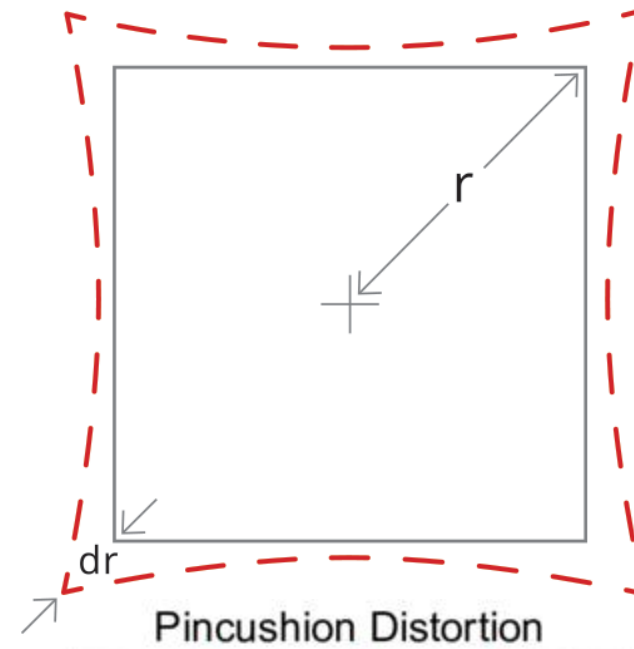
Reduced contrast, reduced resolution

- Effects
 - Loss of sharpness (blurring)
 - Reduced contrast (haze)
 - Washed-out colors
- Correction possibilities
 - Aperture reduction
 - Replacement of lens
 - Software correction



Distortion

- Effects
 - Image deformation
- Correction possibilities
 - Replacement of lens
 - Correction lens
 - Software correction

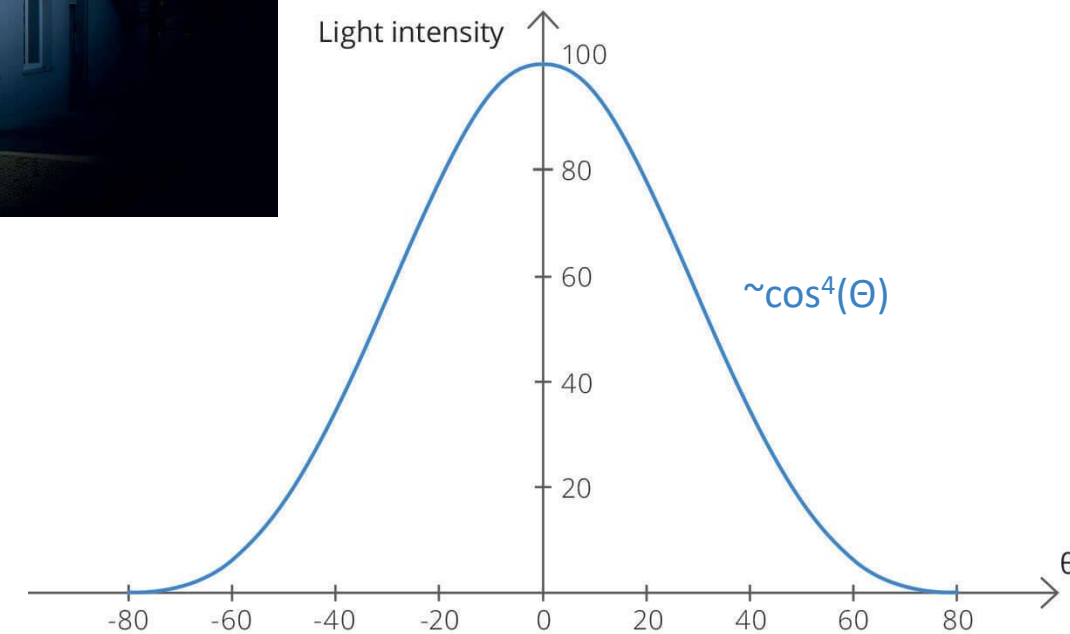


Barrel Distortion



Vignetting

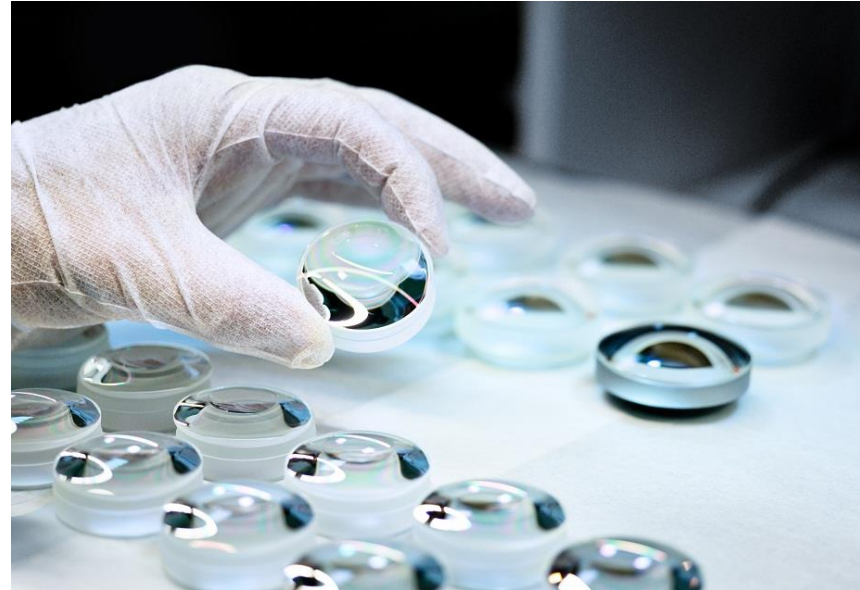
- Effects
 - Decreasing intensity by angle of incidence
- Correction possibilities
 - Aperture increase
 - Decreased FoV
 - Software correction



Optics manufacturers

- **Some relevant optics manufacturers**

- Carl Zeiss AG: zeiss.com
- Nikon Corporation: nikon.com
- Thorlabs, Inc.: thorlabs.com
- Edmund Optics: edmundoptics.com
- Schott AG: schott.com
- Corning Incorporated: corning.com
- Jenoptik AG: jenoptik.com
- Olympus Corporation: olympus-global.com
- Leica Microsystems: leica-microsystems.com
- Canon Inc.: global.canon.com



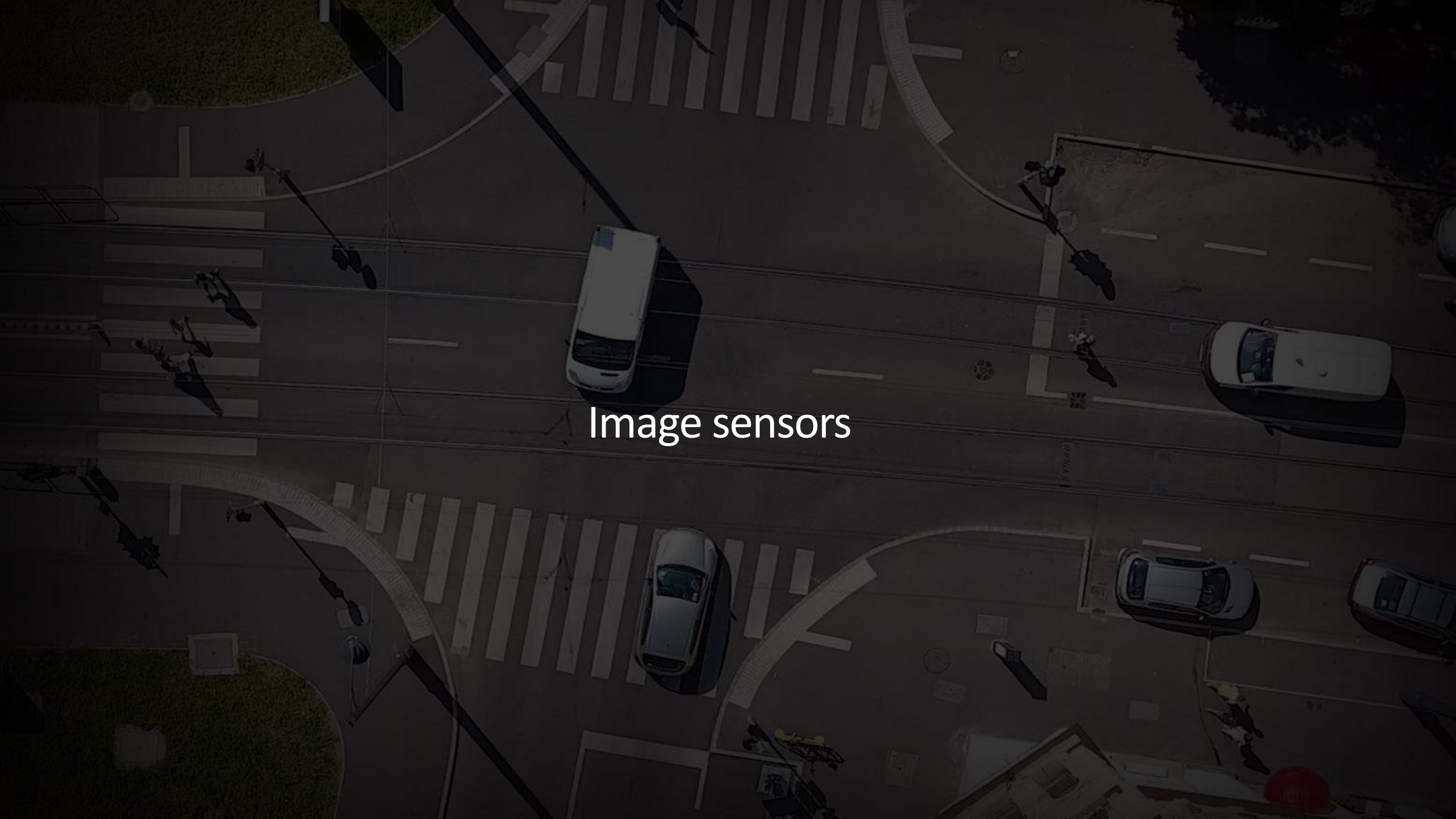
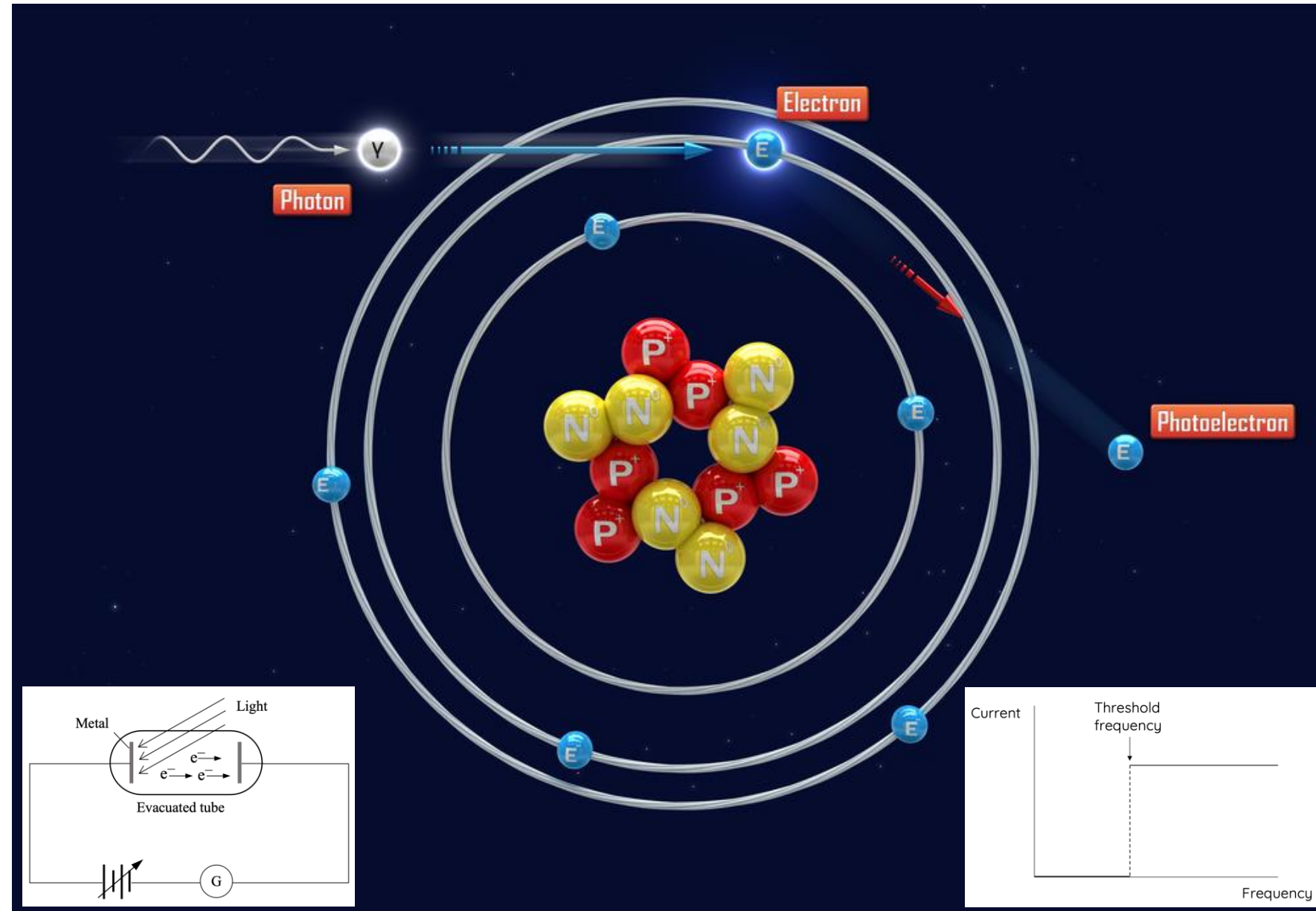


Image sensors

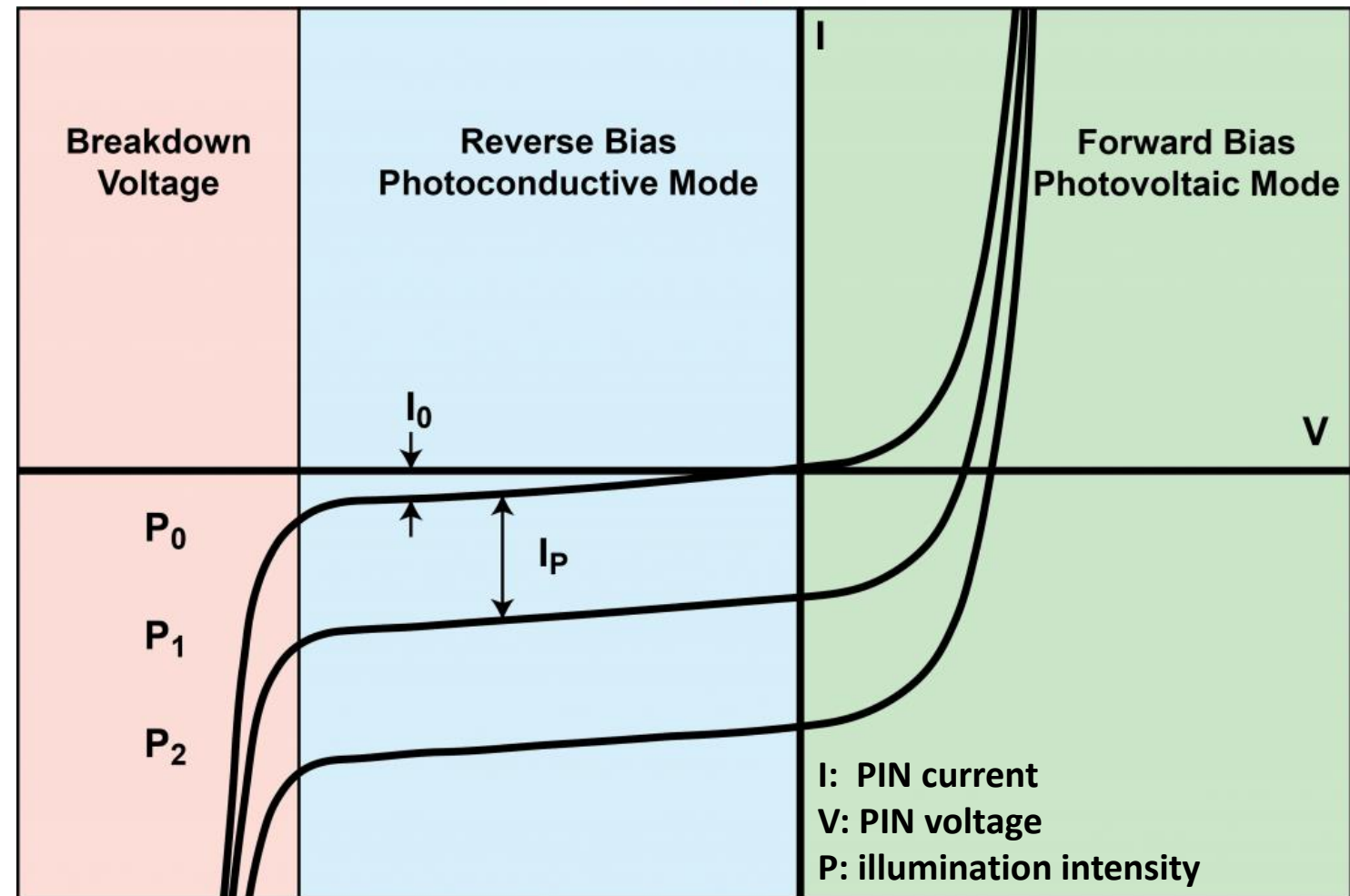
The photoelectric effect

- Electromagnetic radiation can cause electron emission (H. Hertz)
- P. Lenard's experiment results disagreed with classical electromagnetism
- The phenomenon is frequency dependent
- A. Einstein's quantum model of light
Nobel Prize (1921)
- Material absorbs photons ($E=hf$) and emits (photo)electrons, if $E >$ work function



Photodetector

- Semiconductor device to transform optical signal to electrons, a kind of diode
- PN junction of large area & shallow junction depth
- Operating under reverse voltage
- No light → low reverse current = dark current
- Photons generate electron-hole pairs
- Reverse current = photocurrent ~ light intensity
(not voltage)
- [Theory](#)



PIN photodiode

Quantum efficiency

- Different materials for different applications
 - Silicon (Si)
 - Germanium (Ge)
 - Indium Gallium Arsenide (InGaAs)
 - Gallium Arsenide (GaAs)
 - ... and many others
- Spectral responsivity (R): [A/W]
 - Intensity to current conversion
- Quantum efficiency (η): []
 - Photon to photoelectron conversion

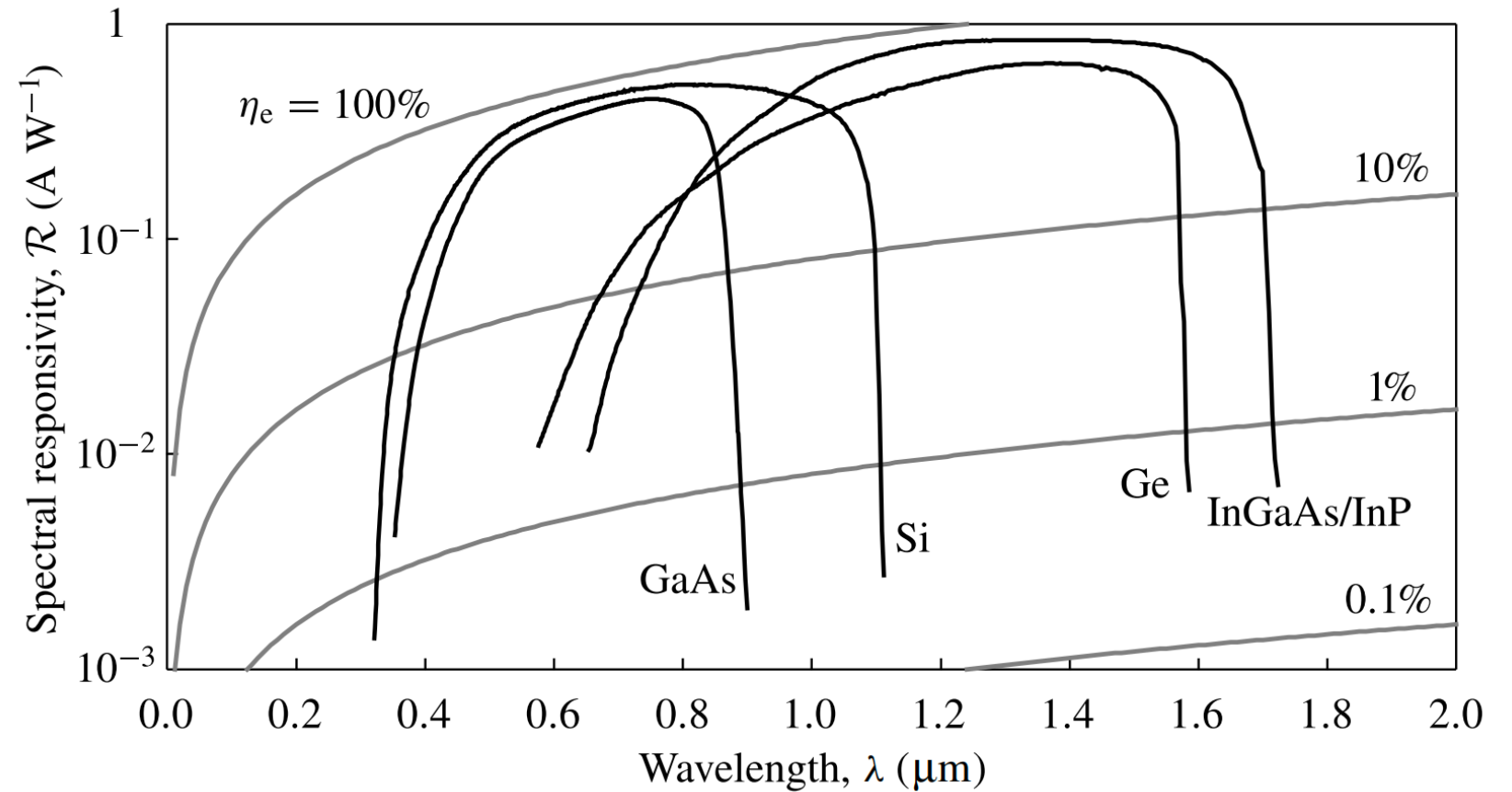
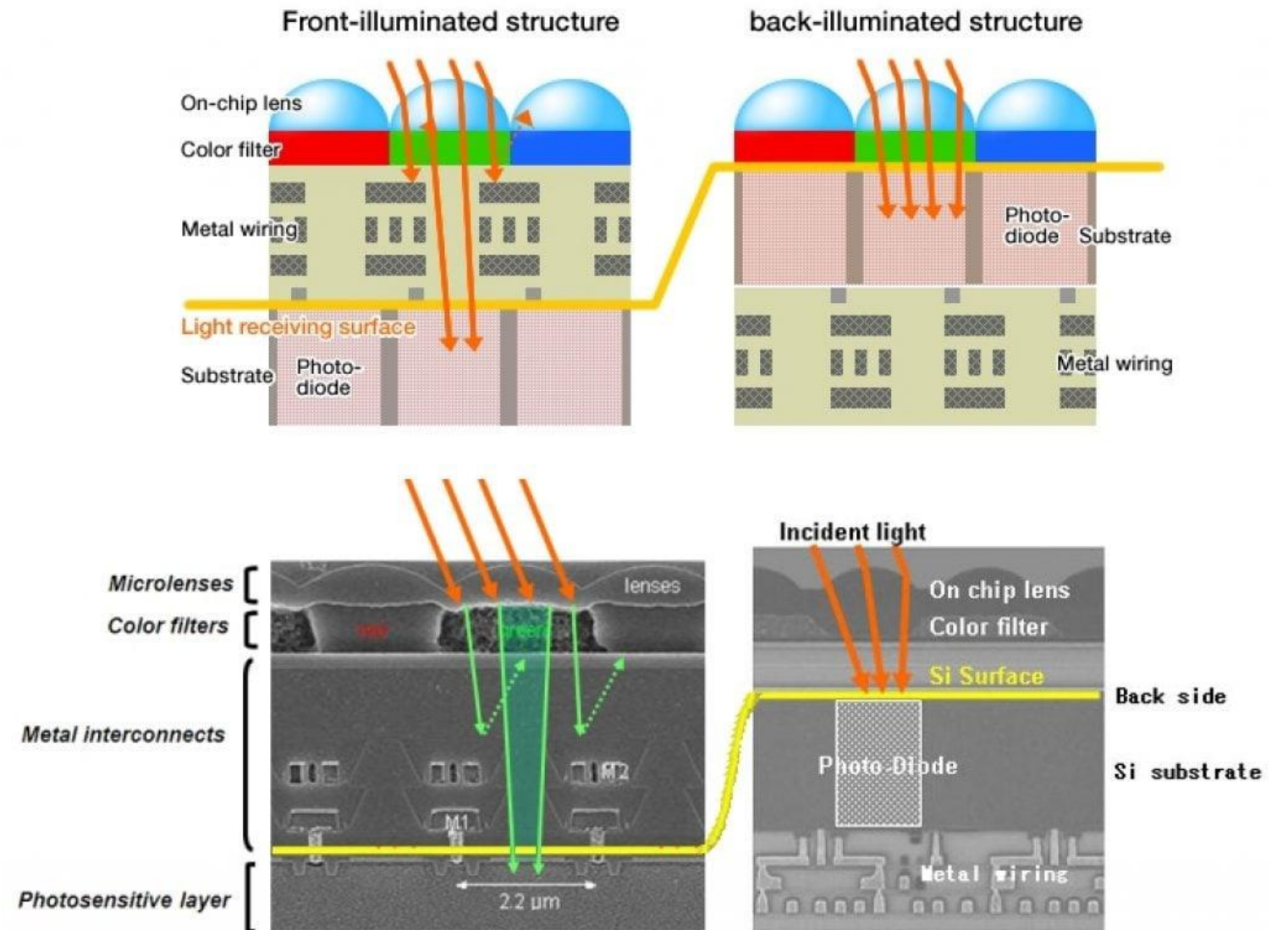


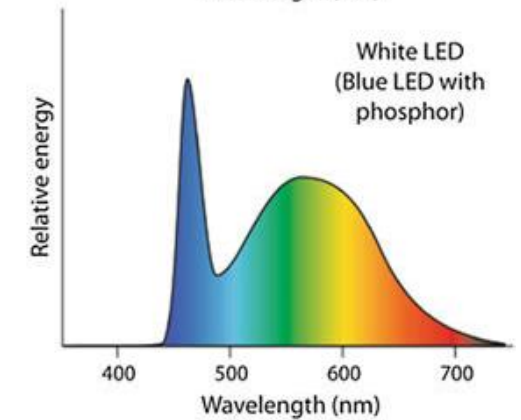
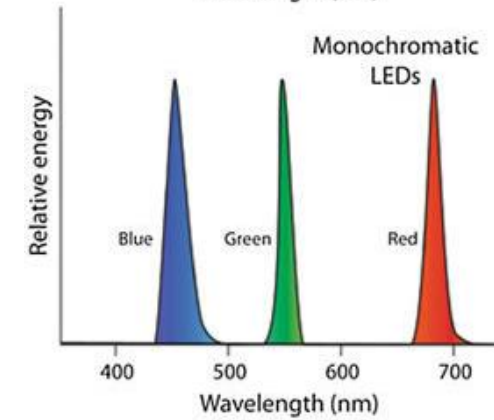
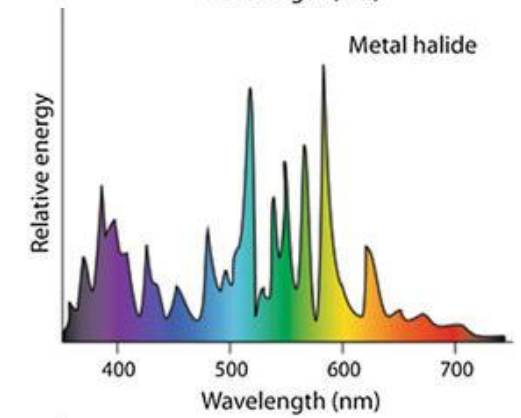
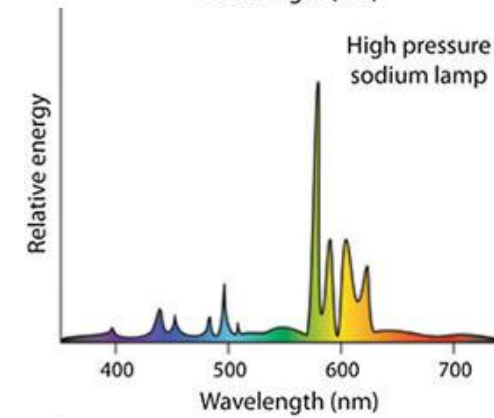
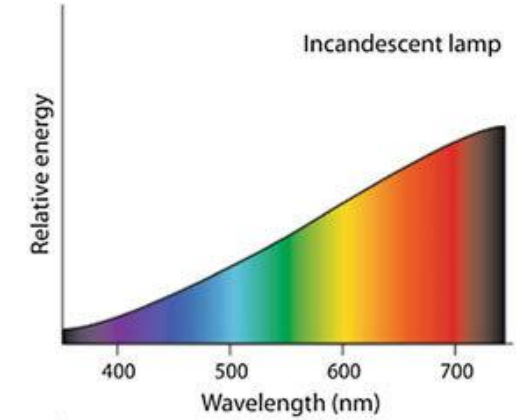
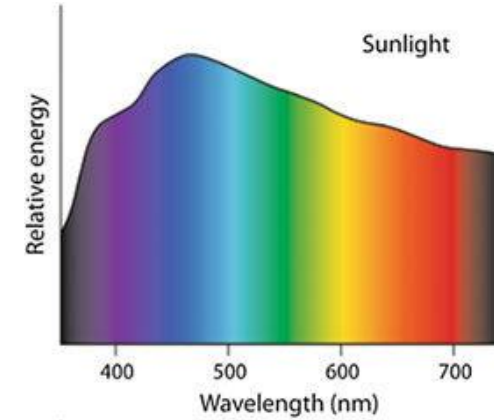
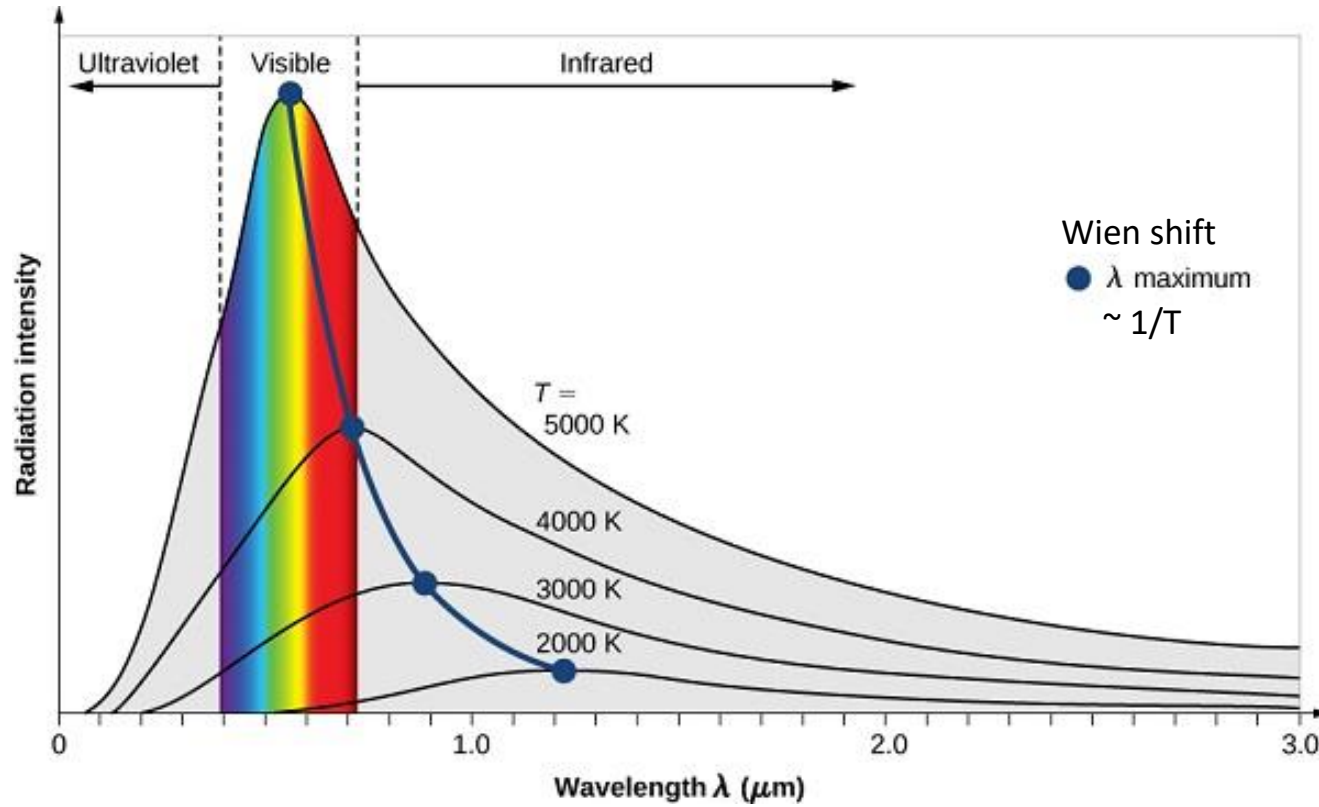
Image sensor

- Main components of a pixel
 - Microlens array
 - Color filter
 - Photodiode
 - Electronics
- Sensor Architecture
 - Front-side illuminated
 - Back-side illuminated
- Sensor technology
 - Charge coupled device
 - Complementary metal-oxide semiconductor

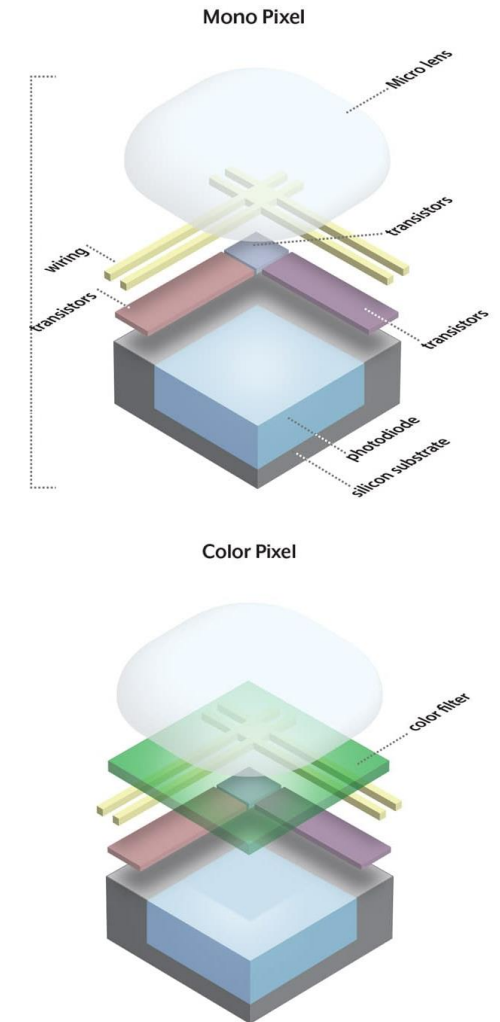
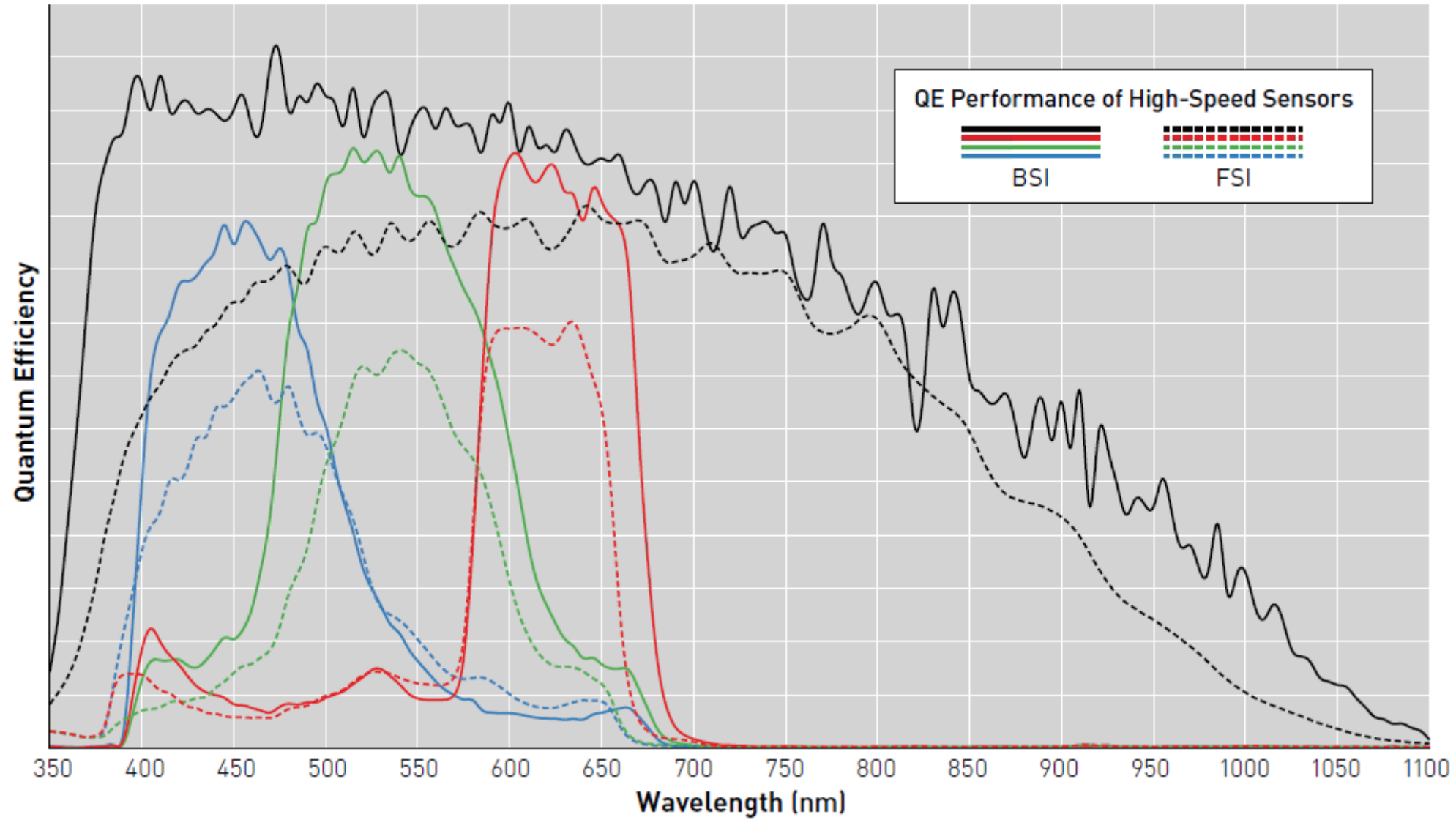


Illumination spectrum

Black-body radiation



Quantum efficiency plot



Quantum efficiency plot

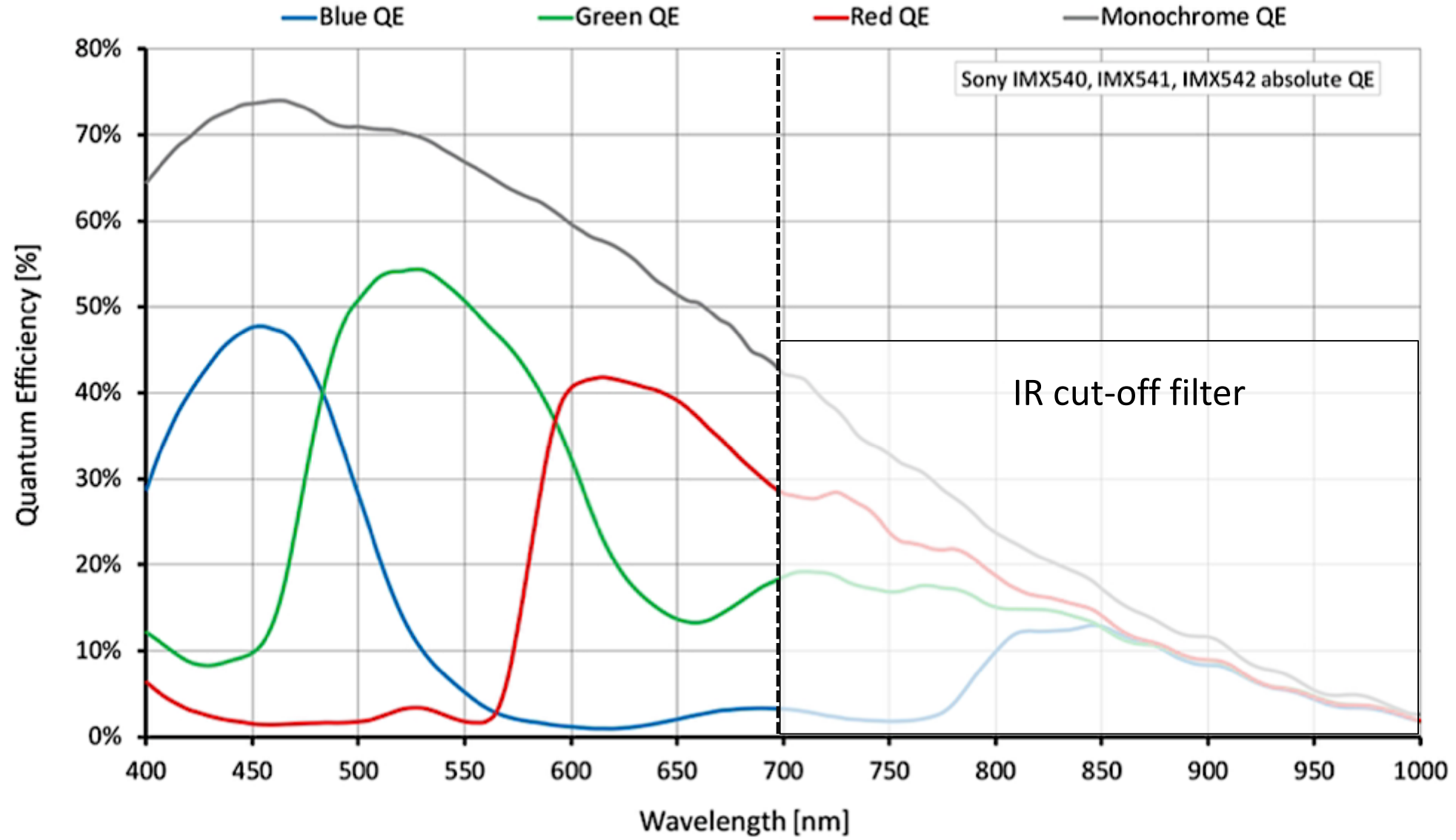
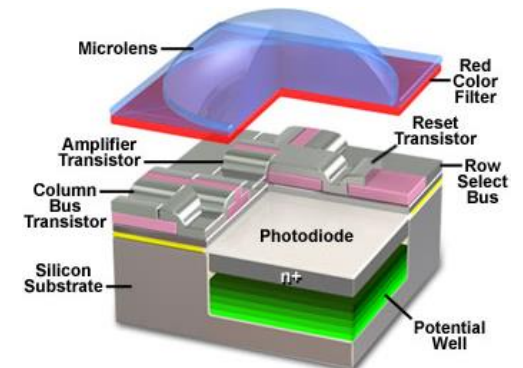
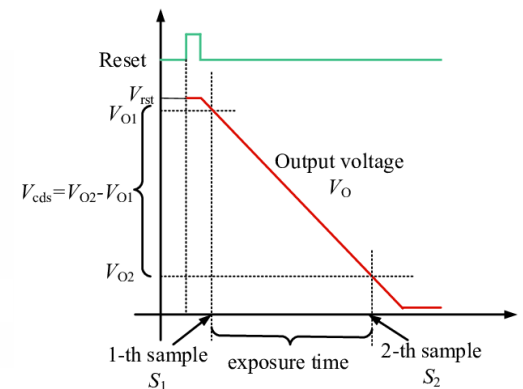
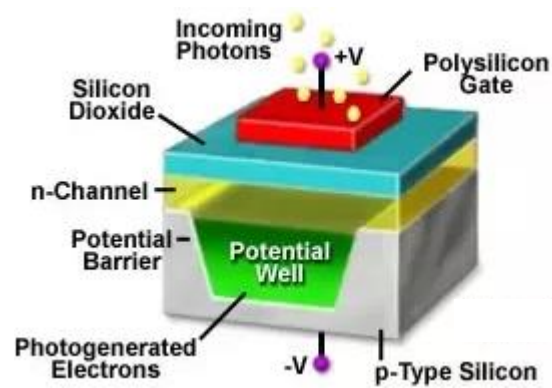
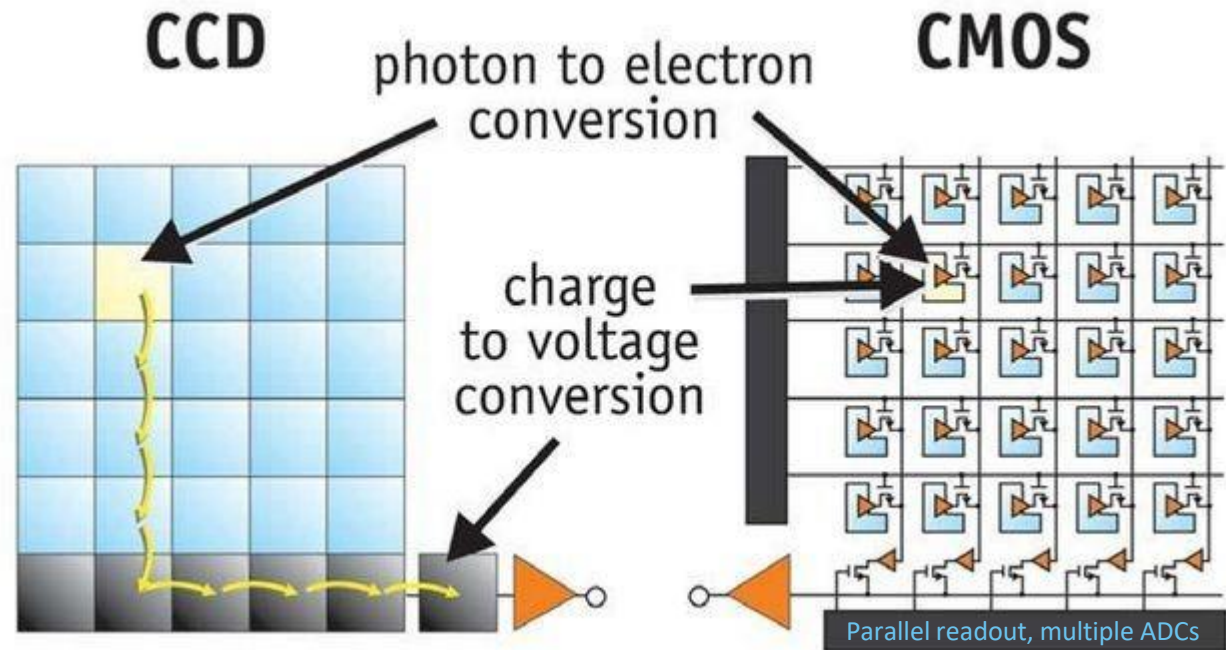


Image sensors

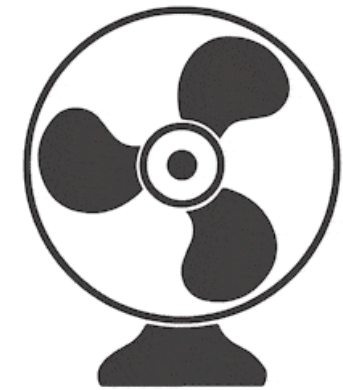
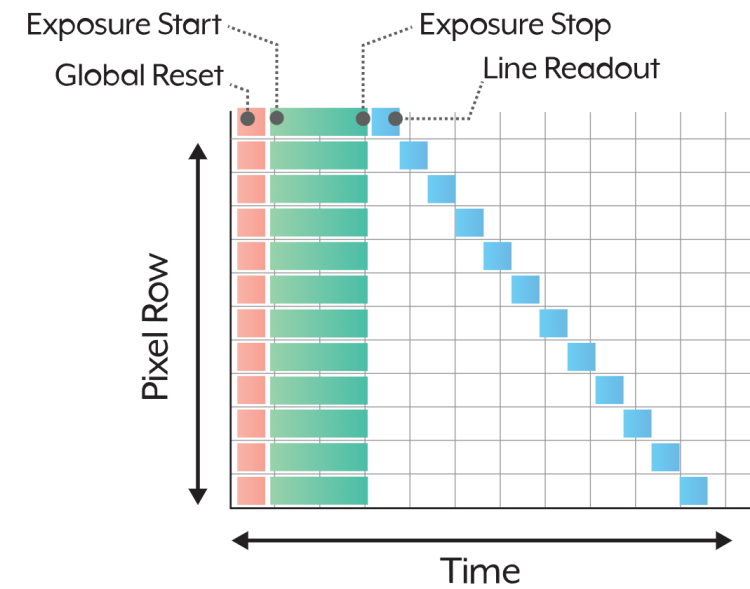
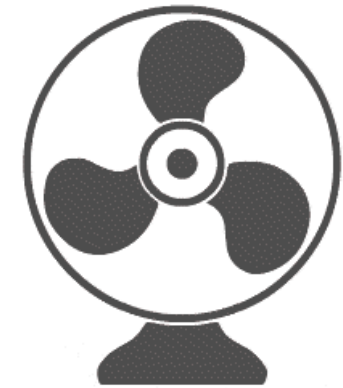
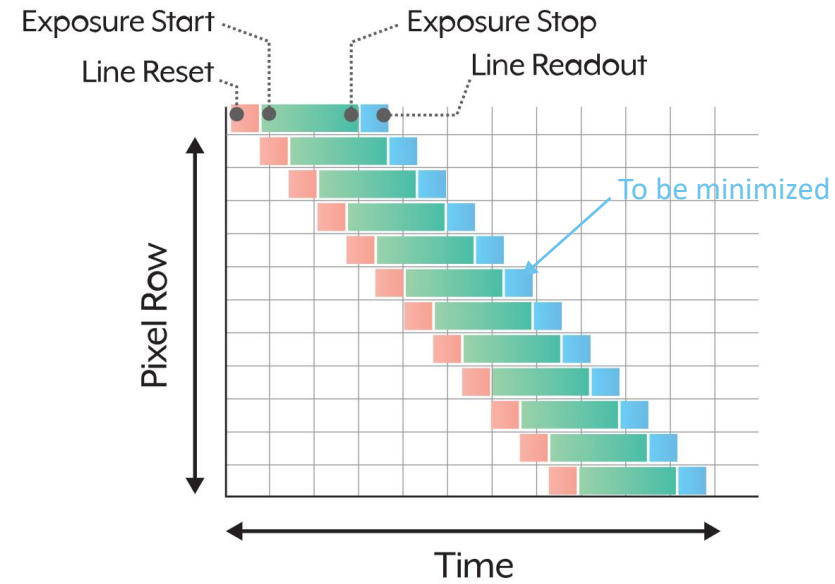
- Charge coupled device (CCD)
 - Higher sensitivity
 - Higher uniformity
- Complementary metal-oxide semiconductor (CMOS)
 - Faster readout and ROI
 - Higher integrability (SoC)
 - Lower power consumption
 - Lower manufacturing cost

• [Video](#)



Shutter types

- Shutter types
 - Rolling shutter
 - Typically CMOS
 - Motion artifacts
 - Synchronization issues
 - Global shutter
 - Typically CCD
 - Lower frame rates
 - Higher power consumption



Typical image sensor sizes

Pixel size:	14µm	10µm	7µm	6,5µm	4,6µm	3,5µm	2,2µm
Pixel area:	196 µm ²	100 µm ²	49 µm ²	36 µm ²	21 µm ²	12 µm ²	5 µm ²

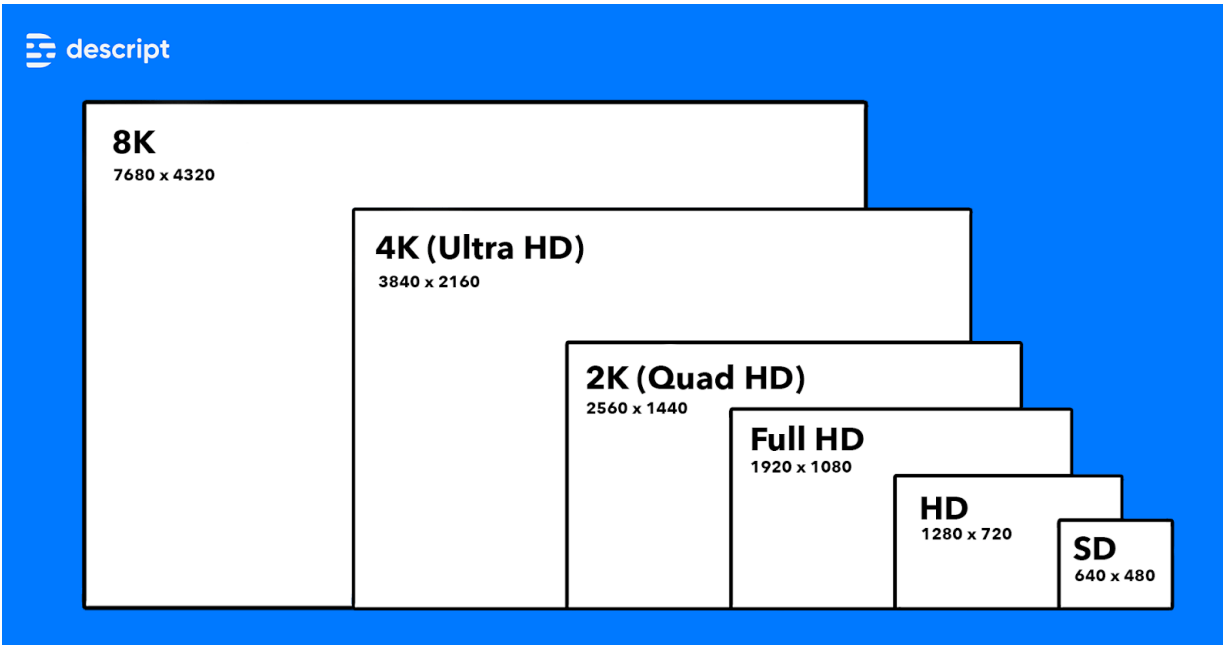
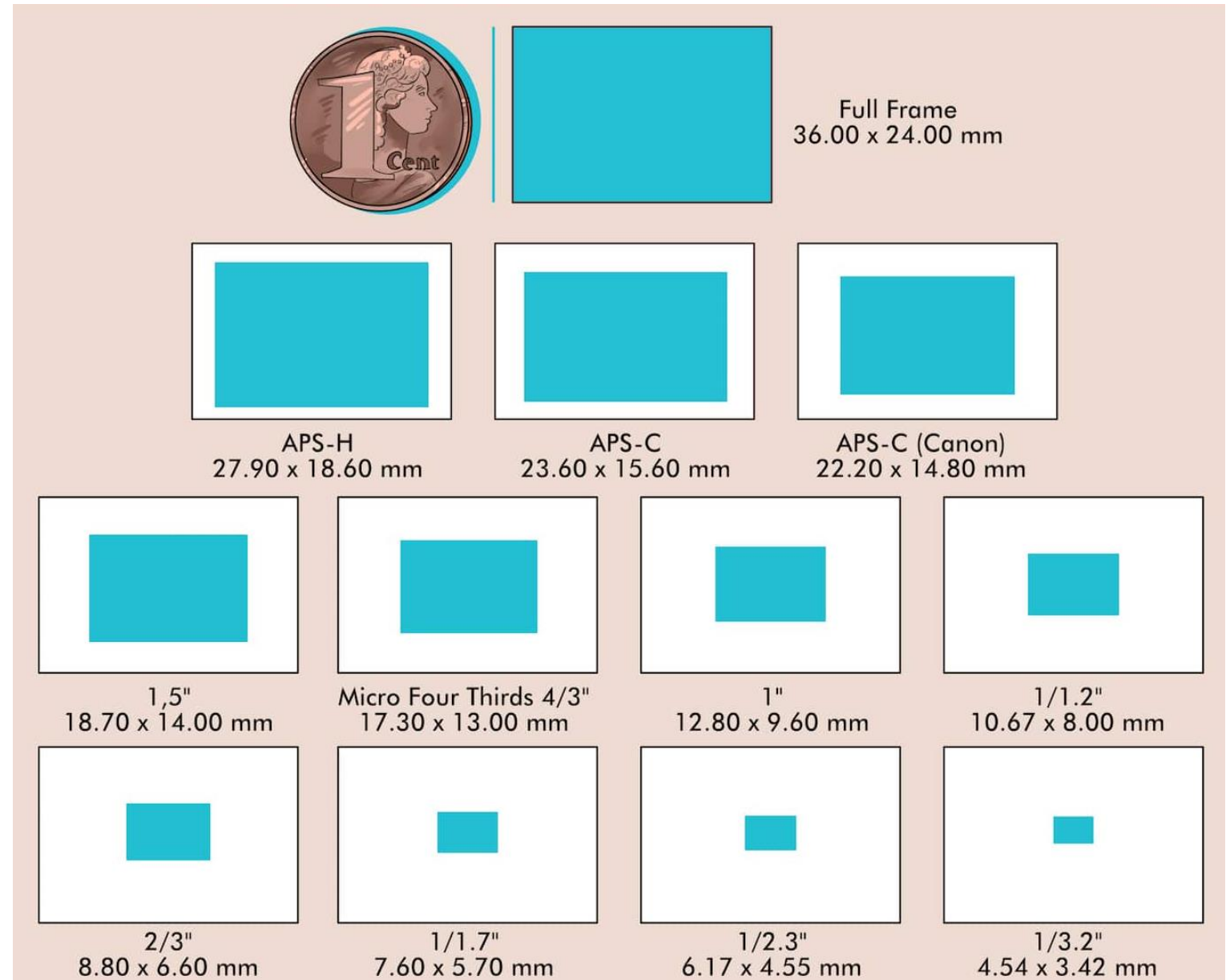
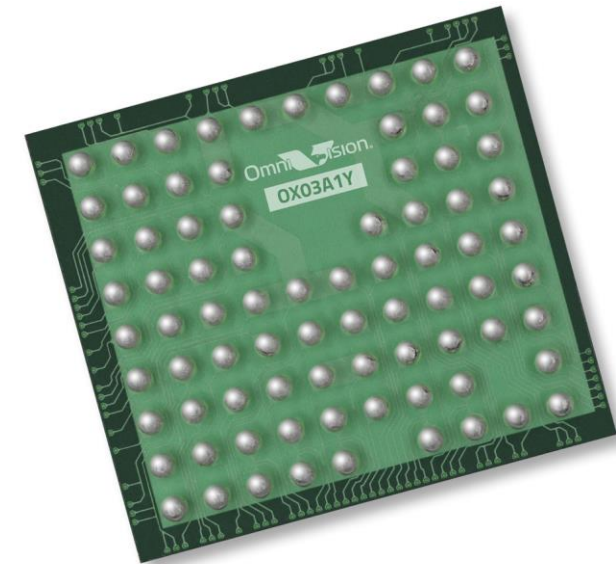
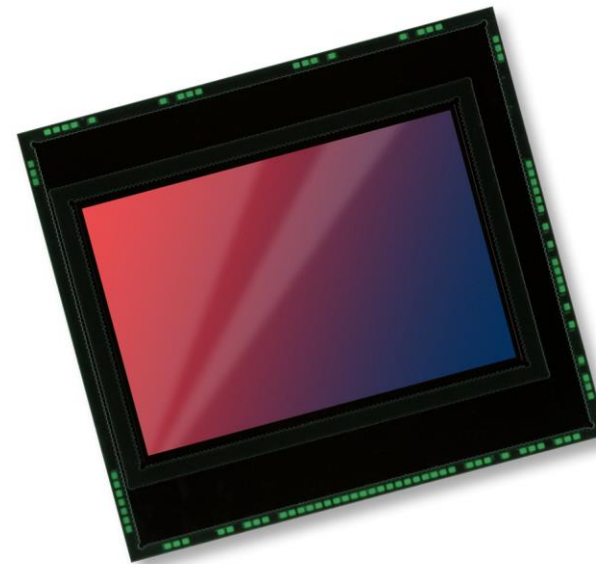
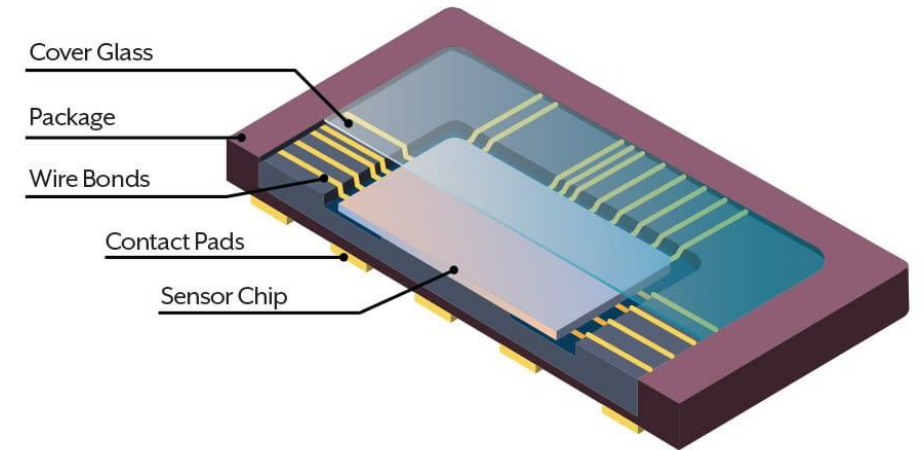
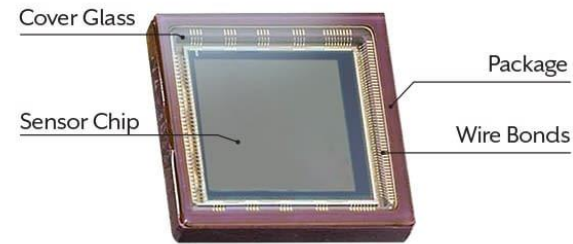


Image sensor providers

- **Some relevant image sensor providers**

- Sony: sony-semicon.co.com *
- Samsung: samsung.com *
- OmniVision: ovt.com *
- ON Semiconductor: onsemi.com *
- Panasonic: panasonic.com *
- STMicroelectronics: st.com *
- Canon: canon.com
- Toshiba: teli.com.jp
- Himax Tech: himax.com.tw
- Teledyne e2v: teledyne-e2v.com
- Pixart Imaging: pixart.com



An aerial, top-down view of a city intersection. The image is dark and semi-transparent, serving as a background for the text. It shows a multi-lane road with a central crosswalk and several cars in motion. Pedestrians are visible on the sidewalks. The overall scene is a complex urban environment with various traffic elements.

Image signal processor and interfaces

Image signal processor

- **Most important features of ISP**

- Sensor data acquisition
- Black level correction
- Noise reduction
- Defective pixel correction
- White balance
- Demosaicing
- Color correction
- Color denoising
- Gamma correction
- Vignetting correction
- Distortion correction
- Edge enhancement
- Auto focus
- High dynamic range (HDR) processing
- Image scaling
- Color space conversion
- Image compression
- Final image formatting
- Metadata generation

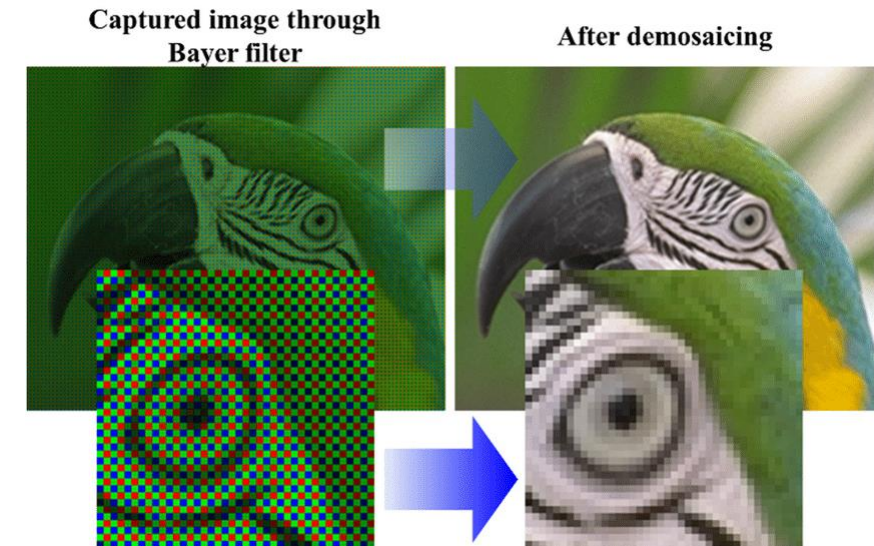
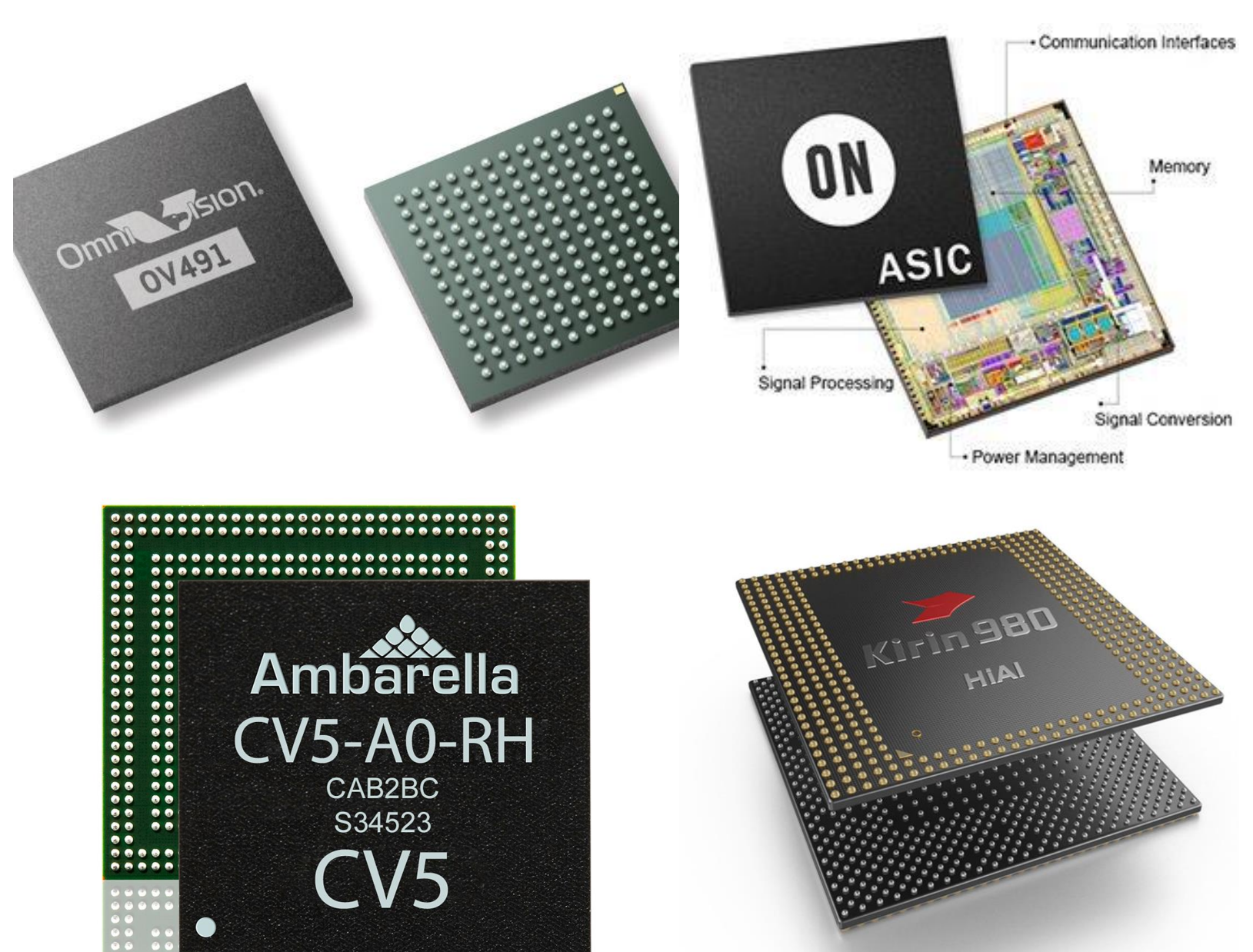


Image signal processor manufacturers

- **Some relevant ISP providers**

- Qualcomm: qualcomm.com *
- Sony: sony-semicon.co.jp *
- Samsung: samsung.com *
- OmniVision: ovt.com *
- Apple: apple.com
- Intel: intel.com
- Huawei: huawei.com
- Nvidia: nvidia.com *
- Ambarella: ambarella.com *
- ST Microelectronics: st.com *
- ON Semiconductor: onsemi.com *
- Texas Instruments: ti.com *



Interfaces and connectors

- **Most common protocols**

- MIPI CSI-2 *
- USB
- LVDS *
- Ethernet *
- PCIe
- CoaXPress
- HDMI/Display port
- Camera Link
- FPD-Link III *
- FireWire (IEEE 1394)
- SDI
- I²C
- SPI



Internal

- **Most common connectors**

- FPC
- MIPI *
- USB
- FAKRA *
- Board-to-Board *
- Coaxial *
- Hirose
- PCIe
- Ethernet (RJ45)
- Automotive Ethernet *
- HDMI/DisplayPort
- FireWire

An aerial, top-down view of a city street intersection. The scene is dimly lit, appearing to be at dusk or dawn. In the center, a white van is driving towards the viewer. To its right, a white sedan is driving away. Further right, another white sedan is visible. In the bottom right corner, a red fire hydrant is visible. The street has white lane markings and crosswalks. Pedestrians are visible on the sidewalks. The overall image has a dark, muted color palette.

Camera performance

EMVA 1288

- EMVA 1288

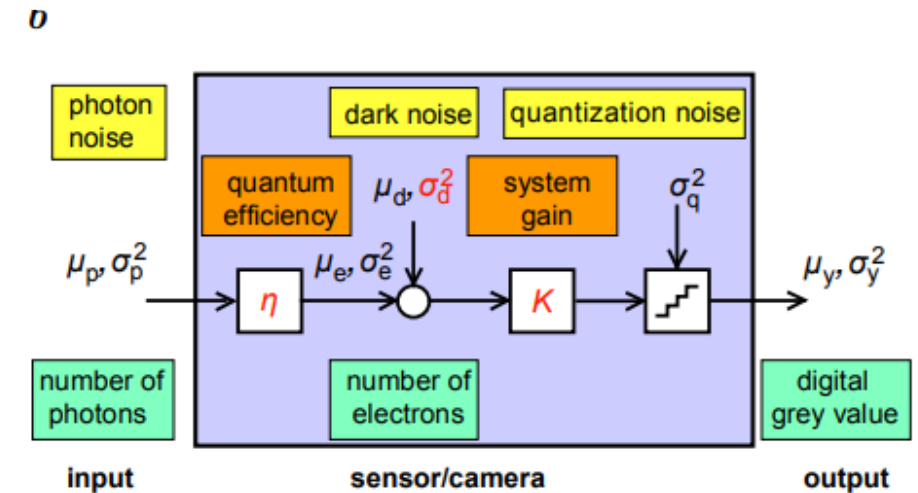
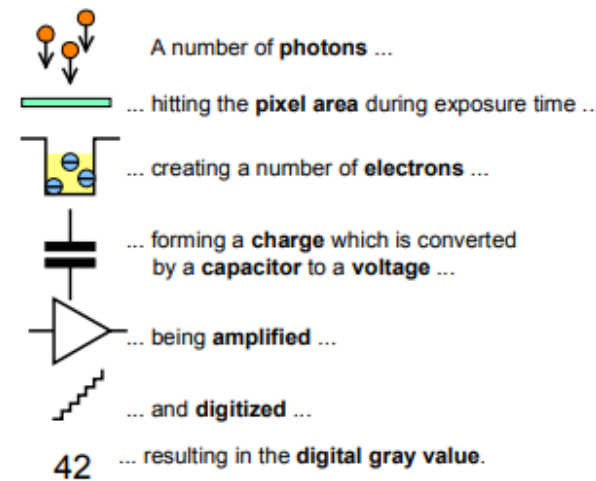
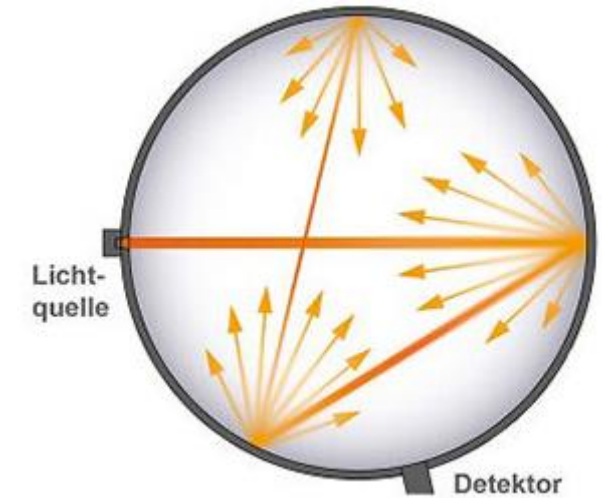
- Standard for characterization of image sensors and cameras

- [Linear characteristics](#)
- [General characteristics](#)

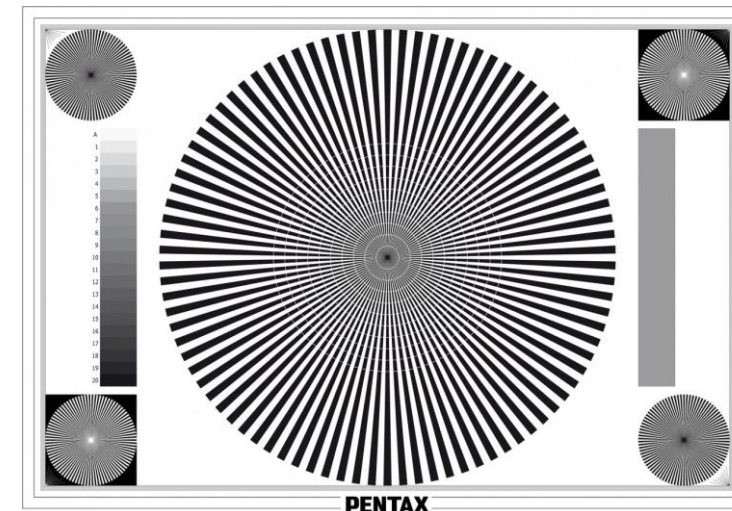
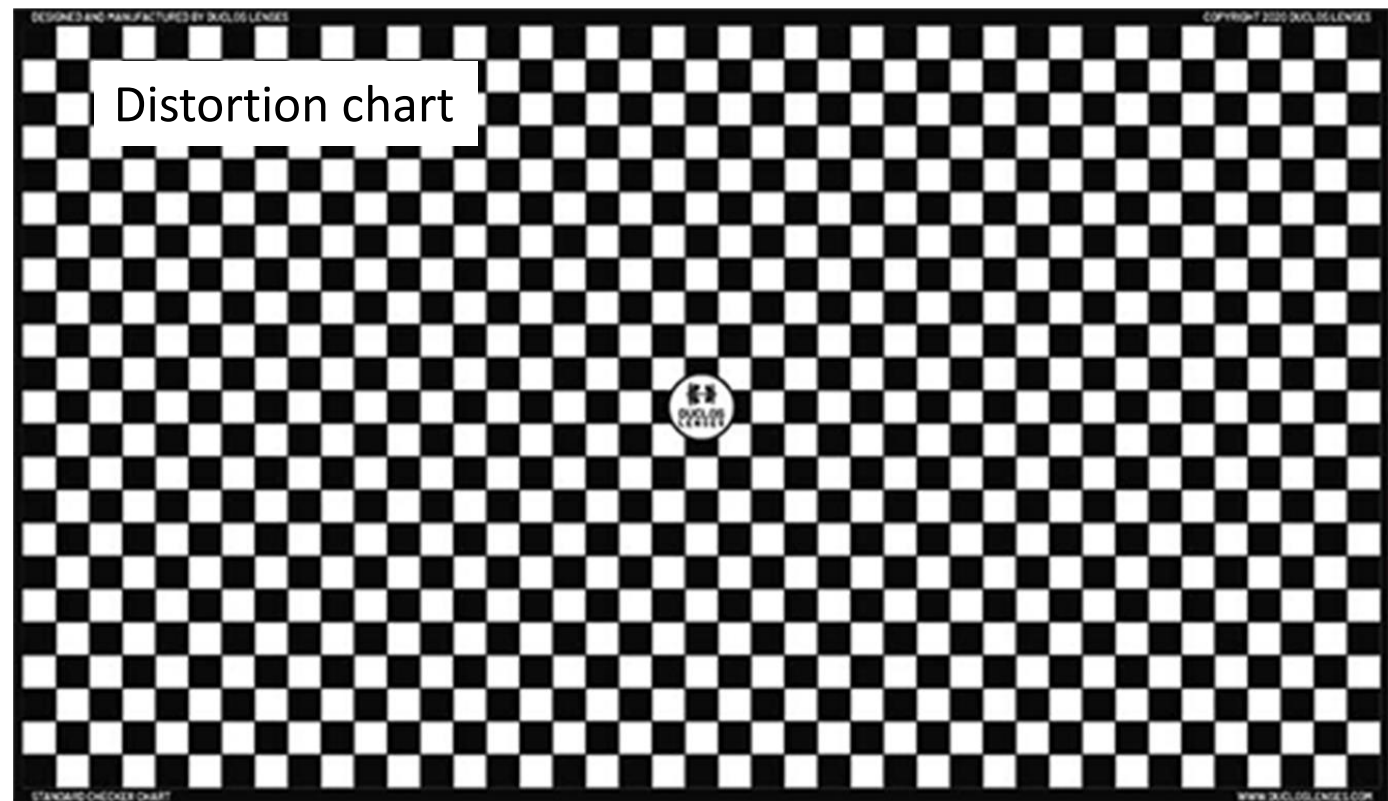
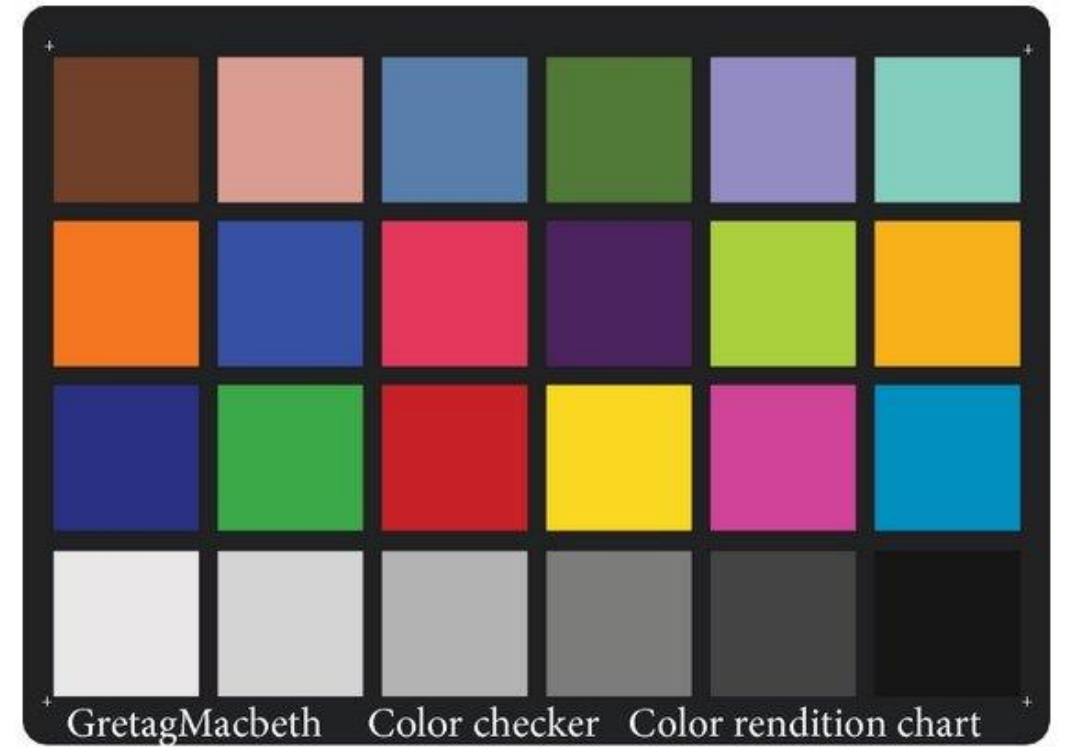
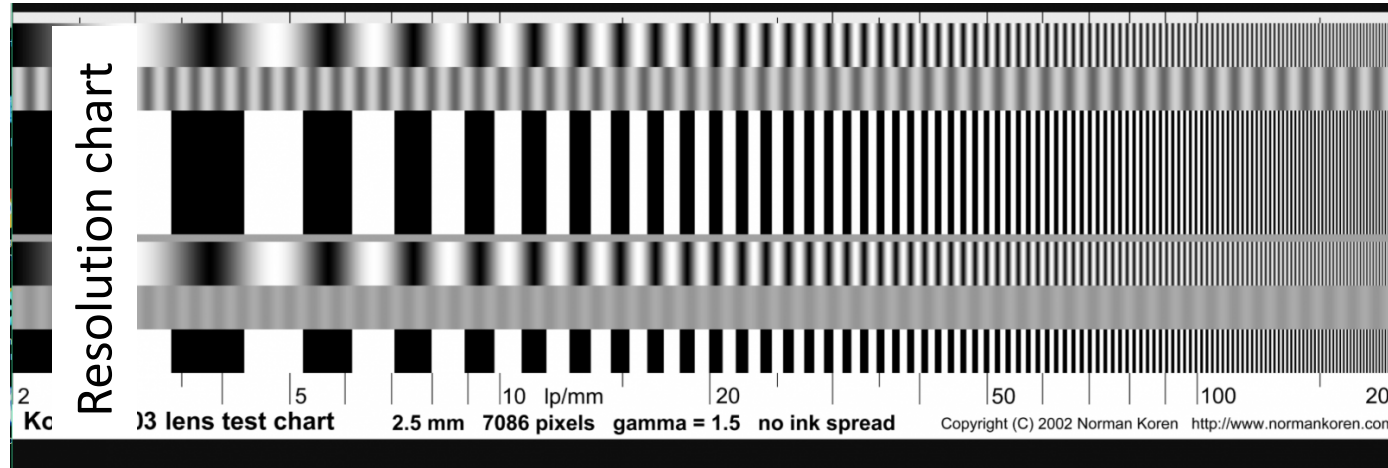
- Measurements for

- Quantum efficiency
- Gain
- Dark noise
- Signal to noise ratio
- Absolute sensitivity ratio
- Saturation capacity
- Dynamic range
- Dark signal nonuniformity
- Photo response nonuniformity
- Non-linearity error
- Dark current

- Companies are following the standard: [Link](#)



Test charts

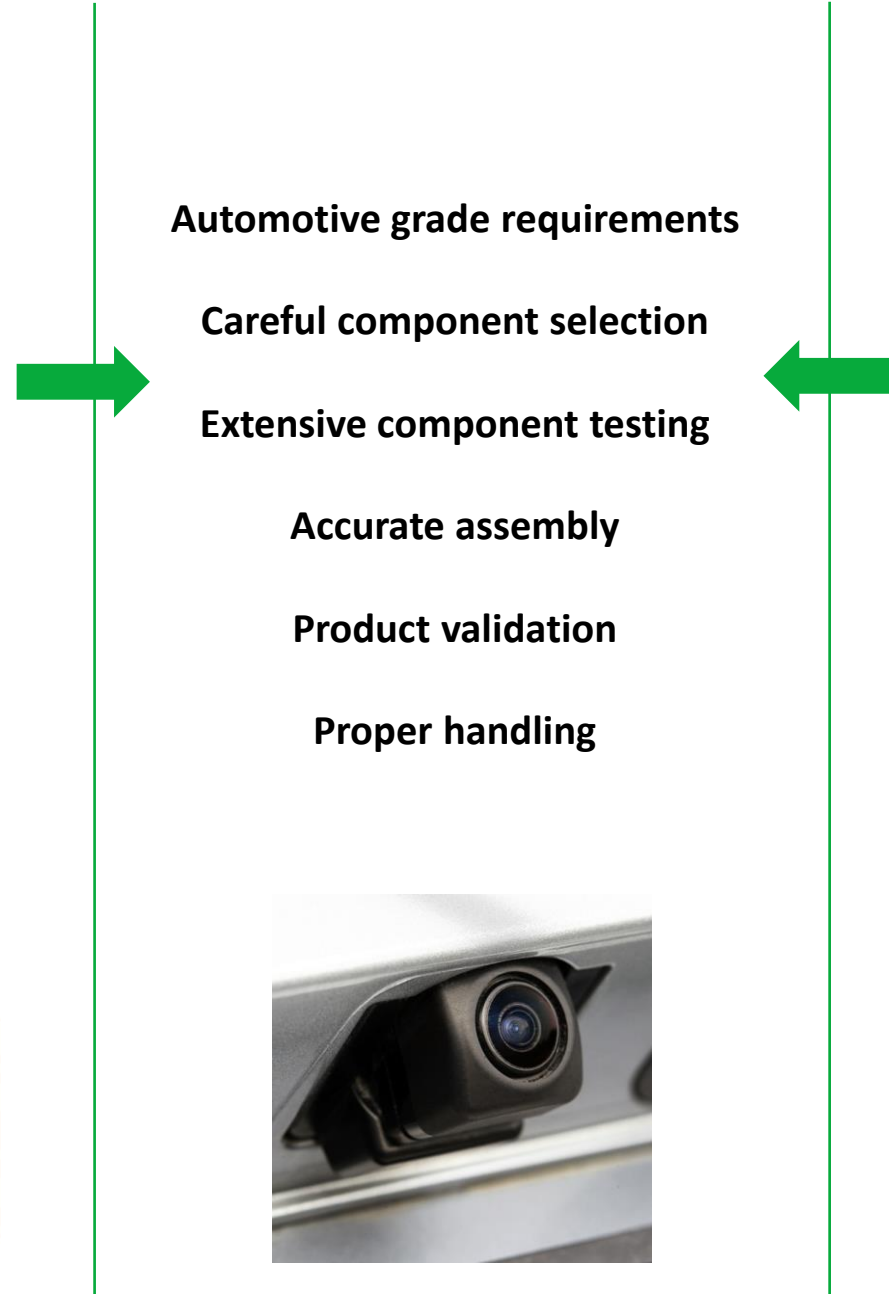
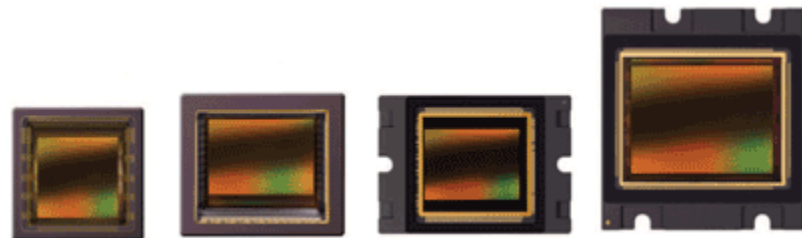


Focus chart

Important camera parameters

- **Some important imaging parameters**

- Sensor- and pixel size
- Resolution
- Bit depth
- Color filter array
- Quantum efficiency
- Sensitivity
- Signal-to-noise ratio
- Dynamic range
- Shutter type
- Frame rate
- Readout speed
- Temperature sensitivity
- Power consumption
- Price
- etc



- **Some important optics parameter**

- Focal length
- Aperture
- Field of view
- Resolution
- Optical coatings
- Optics quality (aberrations)
- Build quality and material
- Size and weight
- Environmental resistance
- Mount type
- Compatibility with image sensor
- Price
- etc



Product tests

- **Product testing before release**
 - Image quality testing
 - Environmental testing
 - Mechanical and durability testing
 - Electrical and signal integrity testing
 - Functional testing
 - Reliability and lifespan testing
 - Compliance and certification testing
 - Performance testing in real-world



An aerial, top-down view of a city street intersection. The image is dark and semi-transparent, serving as a background for the text. It shows a multi-lane road with white lane markings and crosswalks. Several vehicles are visible: a white van in the upper left, a white sedan in the lower center, and a dark SUV in the lower right. Pedestrians are seen crossing the street at various points. Streetlights and traffic signals are also visible. The overall scene is a typical urban intersection.

Automotive camera types

Camera optics

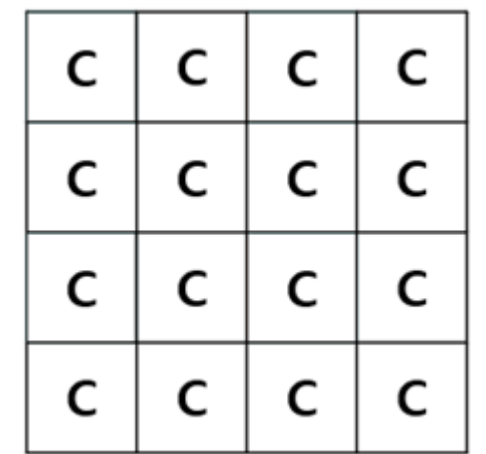
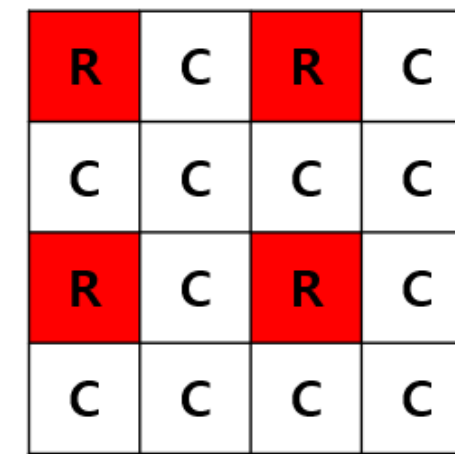
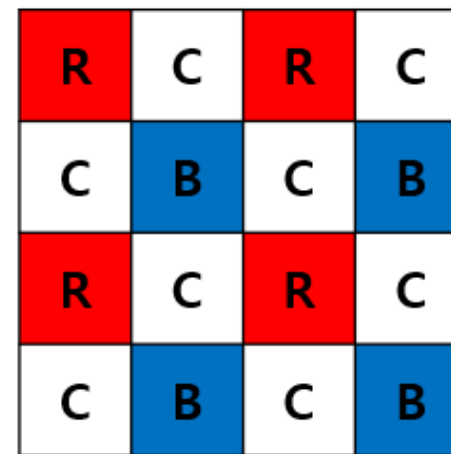
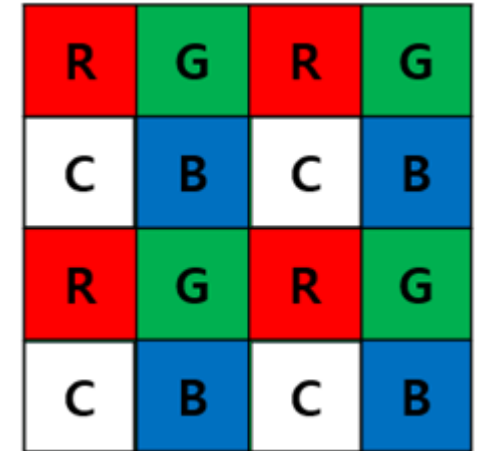
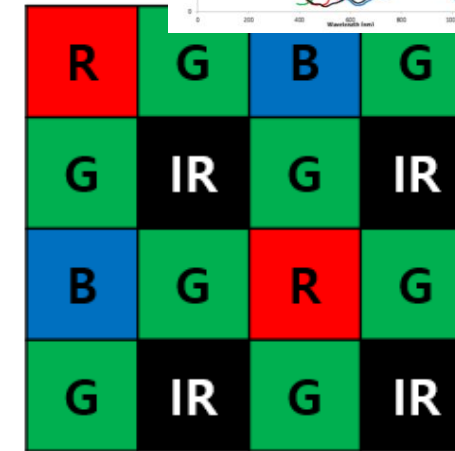
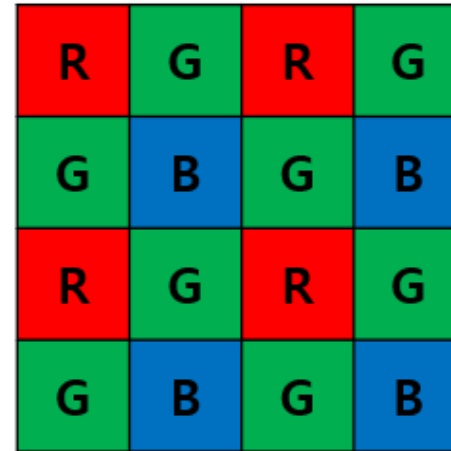
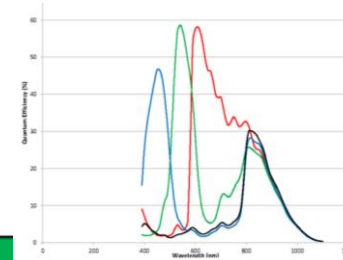
- **Typical camera optics in autonomous vehicles**
 - Long-range cameras
 - FoV: 30 – 60°
 - Long-range
 - Pinhole camera model
 - Wide-angle cameras
 - FoV: 90 – 120°
 - Mid-range
 - Wide-angle camera model
 - Surround cameras
 - FoV: > 180°
 - Close-range
 - Fisheye or ocam camera model



Color filter arrays

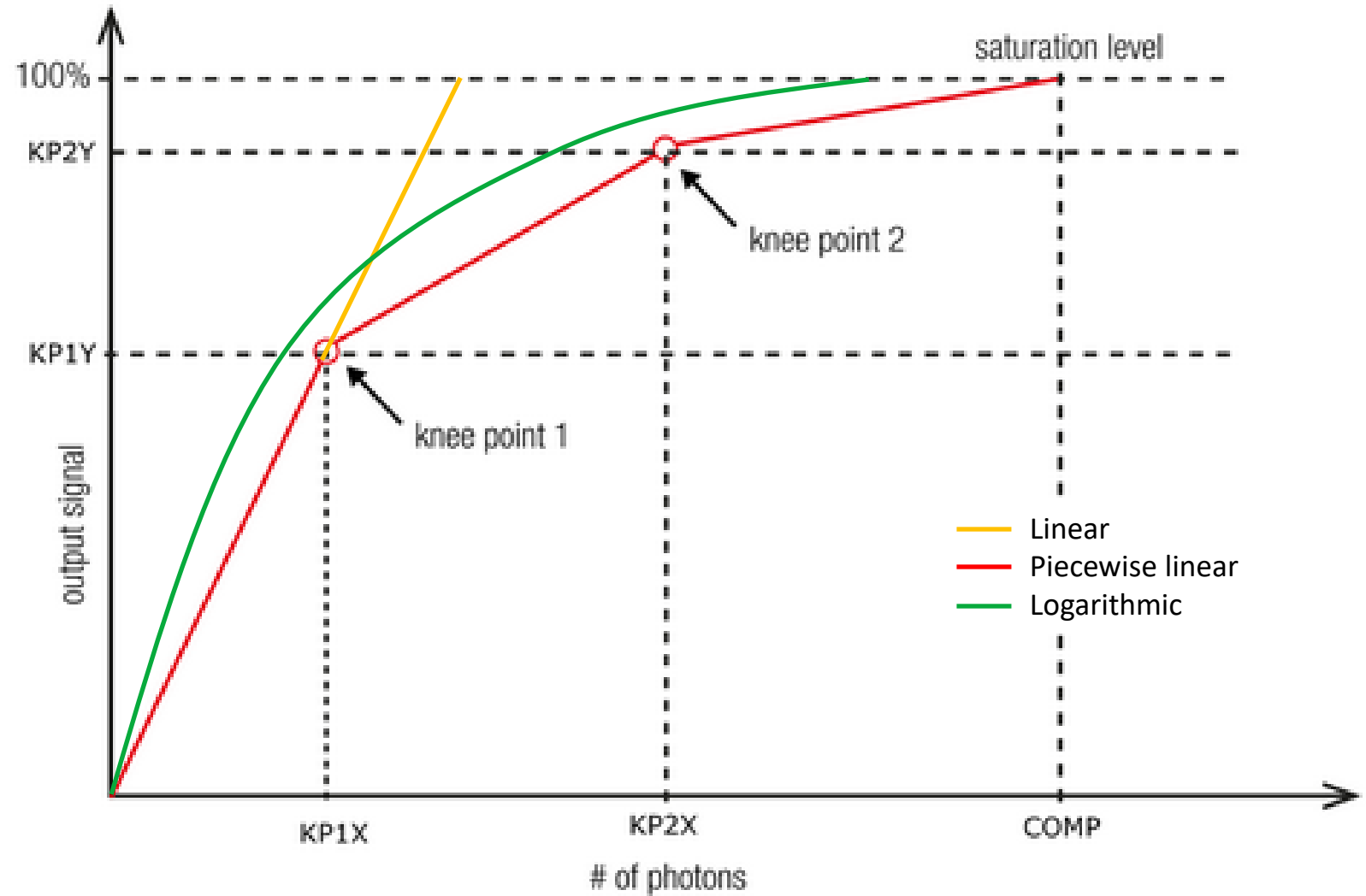
- **Typical CFAs in autonomous vehicles**

- **RGGB (Bayer filter)**
 - Standard for color accuracy
- **RGBIr**
 - Color + enhanced low-light perf.
- **RGCB (Panchromatic)**
 - Color + enhanced low-light perf.
- **RCCB**
 - Balance between sens. and color inf.
- **RCCC**
 - Sensitivity with minimal color inf.
- **CCCC (Monochrome)**
 - Maximizes sensitivity



High dynamic range

- **HDR image generation**
 - High well depth
 - Single exposure
 - Linear characteristics
 - 70 – 90 dB
 - Multi-exposure method
 - Typically 3 – 4 exposures
 - Piecewise linear characteristics
 - 120 – 140 dB
 - Nonlinear image sensor
 - Single exposure
 - Logarithmic characteristics
 - 100 – 120 dB

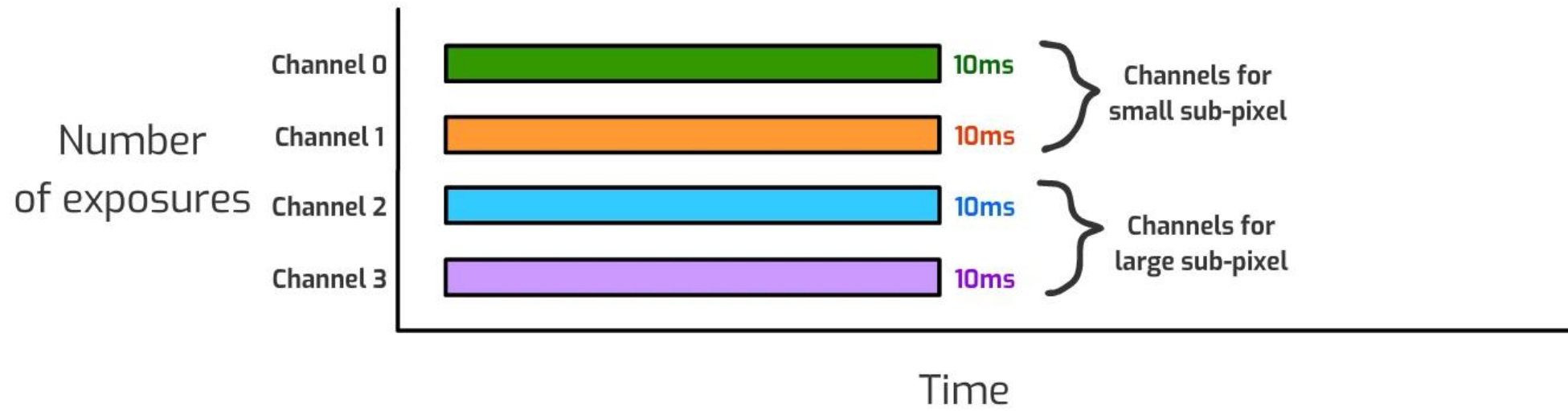


High dynamic range



High dynamic range

IMX490 HDR Simultaneous Exposure



HDR Image
No motion artifacts

LED flicker mitigation

.

LED flicker mitigation

Cameras

- **Some relevant automotive camera manufacturers**

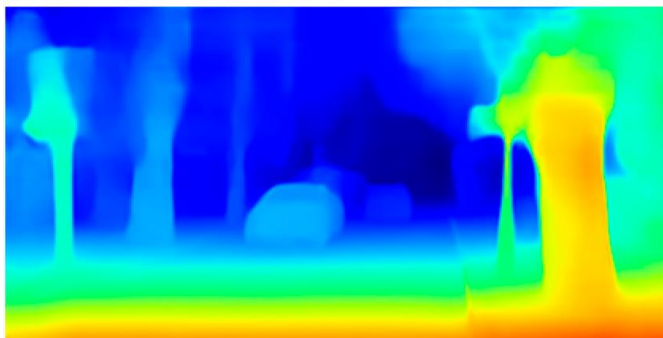
- Bosch
- Continental
- Magna
- ZF Friedrichshafen
- Valeo
- Autoliv / Veoneer
- Mobileye
- Sony
- Aptiv
- Denso



Stereo cameras

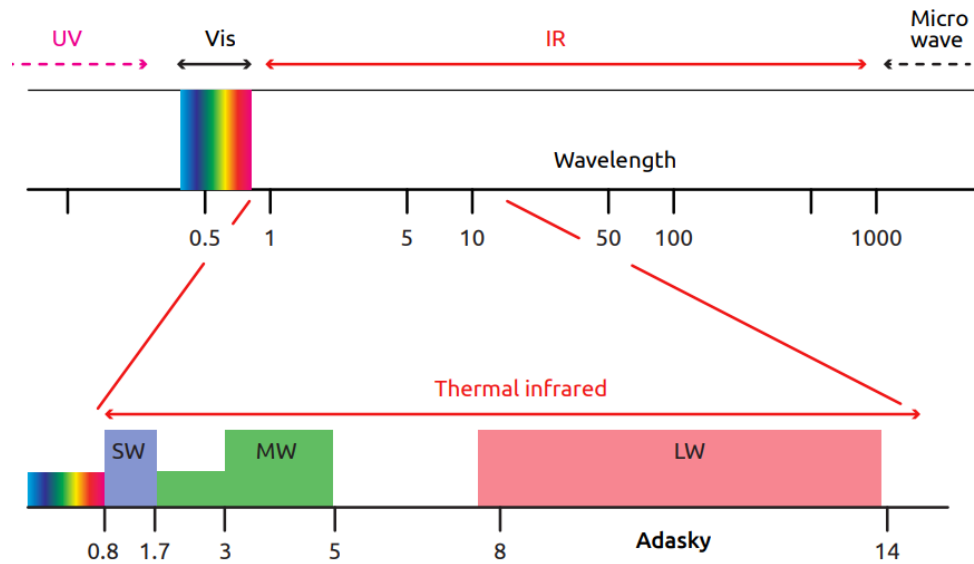
- **Some relevant automotive stereo camera manufacturers**

- Bosch
- Continental
- Autoliv / Veoneer
- Denso



Infrared cameras

- Some relevant infrared camera manufacturers for autonomous vehicles
 - Teledyne FLIR
 - Adasky
- How to apply in bad weather conditions?



Can you understand the scene?

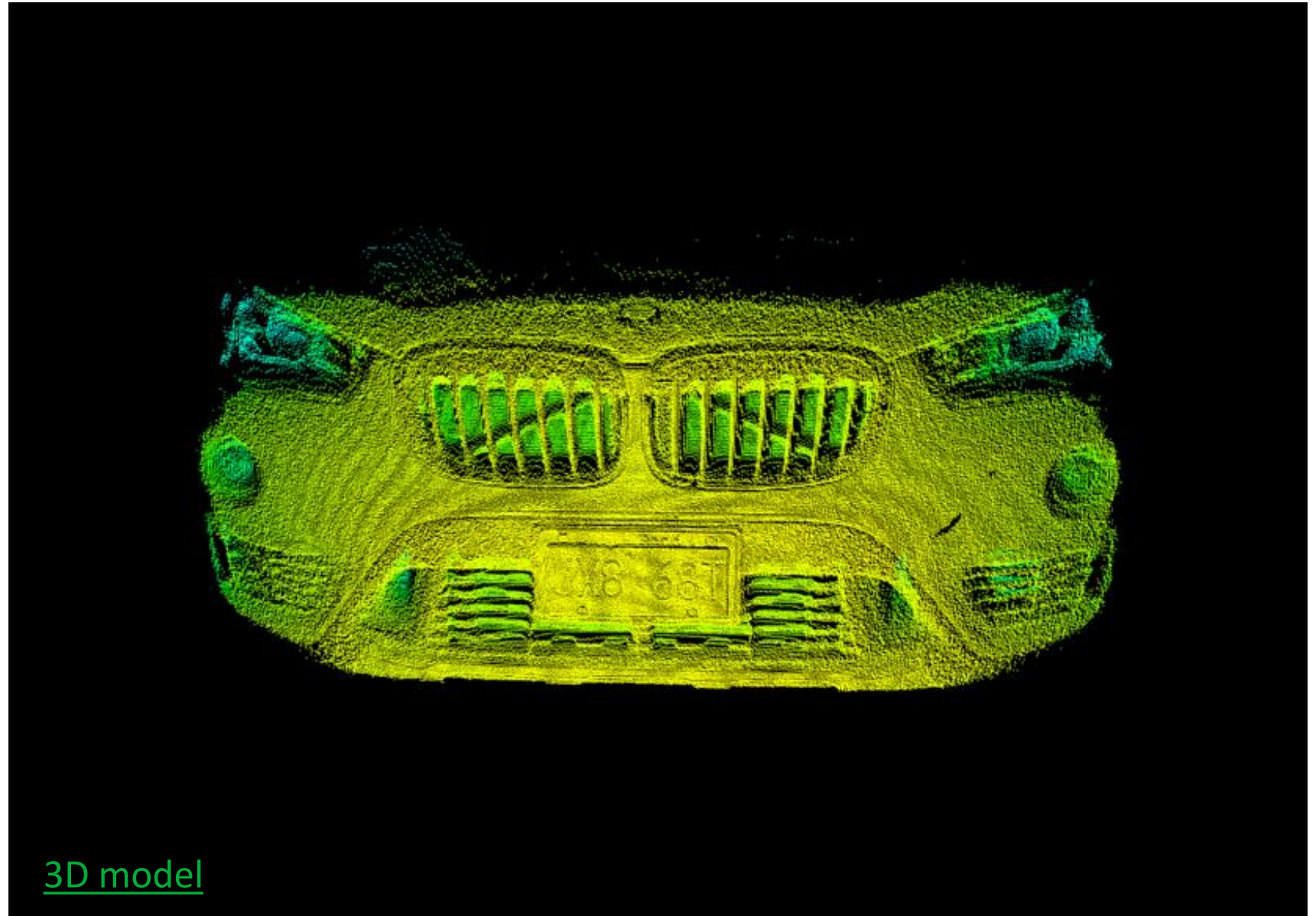


And now?



Time of flight cameras

- **Time of flight cameras**
 - Time of flight image sensors
 - Infrared light source
 - Very limited range
 - Very limited outdoor performance
 - Not for automotive applications
 - [Video](#)



An aerial, top-down view of a city street intersection. The image is dark and semi-transparent, serving as a background for the text. It shows a multi-lane road with white lane markings and crosswalks. Several cars are visible, including a white van in the upper left, a white sedan in the lower center, and a dark SUV in the lower right. Pedestrians are seen crossing the street at various points. Traffic lights and streetlights are also visible. The overall scene is a busy urban environment.

Q&A